owner’s manual and reference guide
This manual is written for operating Software Version 1.0 or above, and is not suitable for earlier software versions.

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Thank you for choosing the GARMIN GPS 12 MAP—the smallest, easiest-to-use GPS navigator for marine, automotive and outdoor use! The GPS 12 MAP represents GARMIN's continuing commitment to provide quality navigation information in a versatile and user-friendly flexible design you'll enjoy for years. To get the most from your new GPS, take the time to read through the owner's manual in order to understand the operating features of the GPS 12 MAP. This manual is organized into three sections for your convenience:

**Section One** (Getting Started) introduces you to the basic features of the unit and provides a quick-start orientation to the GPS 12 MAP.

**Section Two** (Simulator Tour) provides a step-by-step lesson in how your new GPS 12 MAP would operate in the real world by utilizing the built-in simulator mode.

**Section Three** (Reference) provides details about the advanced features and operations of the GPS 12 MAP by topic.

Before getting started with your GPS, check to see that your GARMIN GPS 12 MAP package includes the following items. If you are missing any parts, please contact your dealer immediately.

**Standard Package:**
- GPS 12 MAP Unit
- Wrist Strap
- GPS 12 MAP Owner’s Manual
- Quick Reference Card
- PC Interface Cable

This product is compatible with optional GARMIN MapSource® software packages, which allow you to download map data using the PC interface cable. See your GARMIN Dealer for detailed information about MapSource options.
CAUTION: The Global Positioning System (GPS) is operated by the government of the United States, which is solely responsible for its accuracy and maintenance. The system is subject to changes which could affect the accuracy and performance of all GPS equipment. Although the GPS 12 MAP is a precision electronic NAVigation AID (NAVAID), any NAVAID can be misused or misinterpreted and, therefore, become unsafe.

WARNING: For vehicular applications, it is the sole responsibility of the owner/operator of the GPS 12 MAP to place and secure the GPS unit so that it will not: interfere with the vehicle operating controls and safety devices, obstruct the operator’s view of driving conditions, or cause damage or personal injury in the event of an accident. Do not mount the GPS 12 MAP over airbag panels or in the field of airbag deployment. Airbags expand with a rapid force that can propel objects in their path towards the vehicle driver or passengers causing possible injury. Do not mount the GPS 12 MAP in a place where the driver or passengers are likely to impact it in an accident or collision. The mounting hardware provided by GARMIN is not warranted against collision damage or the consequences thereof.

WARNING: For vehicular operations, it is the sole responsibility of the operator of the vehicle to operate his or her vehicle in a safe manner, maintain full surveillance of all driving conditions at all times, and never become distracted by the GPS 12 MAP to the exclusion of safe operating practices. It is unsafe to operate the GPS 12 MAP while you are driving. Failure by the operator of a vehicle equipped with a GPS 12 MAP to pay full attention to operating the vehicle and road conditions while the vehicle is in motion could result in an accident or collision with property damage and personal injury.
This device complies with Part 15 of the FCC limits for Class B digital devices. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. Furthermore, there is no guarantee that interference will not occur in a particular installation.

If this equipment does cause harmful interference to other equipment, which can be determined by turning the affected equipment off and on, the user is encouraged to try and correct the interference by relocating the equipment or connecting the equipment to a different circuit than the affected equipment. Consult an authorized dealer or other qualified service technician for additional help if these remedies do not correct the problem.

Operation of this device is subject to the following conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

The GPS 12 MAP does not contain any user-serviceable parts. Repairs should only be made by an authorized GARMIN service center. Unauthorized repairs or modifications could void your warranty and authority to operate this device under Part 15 regulations.
GARMIN Corporation warrants this product to be free from defects in materials and workmanship for one year from the date of purchase. GARMIN will, at its sole option, repair or replace any components which fail in normal use. Such repairs or replacement will be made at no charge to the customer for parts or labor. The customer is, however, responsible for any transportation costs. This warranty does not cover failures due to abuse, misuse, accident or unauthorized alteration or repairs.

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IN NO EVENT SHALL GARMIN BE LIABLE FOR ANY INCIDENTAL, SPECIAL, INDIRECT OR CONSEQUENTIAL DAMAGES, WHETHER RESULTING FROM THE USE, MISUSE OR INABILITY TO USE THIS PRODUCT OR FROM DEFECTS IN THE PRODUCT. SOME STATES DO NOT ALLOW THE EXCLUSIONS OF INCIDENTAL OR CONSEQUENTIAL DAMAGES, SO THE ABOVE LIMITATIONS MAY NOT APPLY TO YOU.

To obtain warranty service, call the GARMIN Customer Service department (913-397-8200) for a returned merchandise tracking number. The unit should be securely packaged with the tracking number clearly marked on the outside of the package, and sent freight prepaid and insured to a GARMIN warranty service station. A copy of the original sales receipt is required as the proof of purchase for warranty repairs. GARMIN retains the exclusive right to repair or replace the unit or software or offer a full refund of the purchase price at its sole discretion. SUCH REMEDY SHALL BE YOUR SOLE AND EXCLUSIVE REMEDY FOR ANY BREACH OF WARRANTY.
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INTRODUCTION

“How To” Index

The list below is provided to help you quickly find some of the more important procedures you will use on your new GPS 12 MAP.

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The GPS 12 MAP is a powerful navigation tool that can guide you anywhere in the world. To better understand its operation and capabilities, it may be helpful to review the basic terms and concepts briefly explained below.

Other navigation and GPS definitions used in this manual are defined in the appropriate reference sections of this manual.

<table>
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<th>Glossary</th>
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<tr>
<td><strong>Almanac Data</strong>—Satellite constellation information (including location) that is transmitted from every GPS satellite. Almanac data must be acquired before GPS navigation can begin.</td>
</tr>
<tr>
<td><strong>Bearing</strong>—The compass direction from your position to a destination.</td>
</tr>
<tr>
<td><strong>Course Made Good (CMG)</strong>—The bearing from the “active from” position (your starting point) to your present position.</td>
</tr>
<tr>
<td><strong>Crosstrack Error (XTK)</strong>—The distance you are off a desired course either left or right.</td>
</tr>
<tr>
<td><strong>Desired Track</strong>—The compass course between the “from” and “to” waypoints.</td>
</tr>
<tr>
<td><strong>Differential GPS (DGPS)</strong>—An extension of the GPS system that uses radio beacons to transmit position corrections to GPS receivers.</td>
</tr>
<tr>
<td><strong>Estimated Time of Arrival (ETA)</strong>—The time of day of your arrival at a destination.</td>
</tr>
<tr>
<td><strong>Estimated Time Enroute (ETE)</strong>—The time left to your destination at your present speed.</td>
</tr>
<tr>
<td><strong>Grid</strong>—Coordinate system that projects the earth on a flat surface, using square zones for position measurements. UTM/UPS and Maidenhead formats are grid systems.</td>
</tr>
<tr>
<td><strong>Ground Speed</strong>—The velocity you are traveling relative to a ground position.</td>
</tr>
<tr>
<td><strong>Latitude</strong>—The north/south measurement of position perpendicular to the earth’s polar axis.</td>
</tr>
<tr>
<td><strong>Longitude</strong>—The east/west measurement of position referenced to the Prime Meridian (0° longitude) which goes through Greenwich, England.</td>
</tr>
<tr>
<td><strong>Navigation</strong>—The process of traveling from one place to another and knowing where you are in relation to your desired course and/or destination.</td>
</tr>
<tr>
<td><strong>Position</strong>—An exact, unique location based on a geographic coordinate system.</td>
</tr>
<tr>
<td><strong>Track (TRK)</strong>—The direction of movement relative to a ground position.</td>
</tr>
<tr>
<td><strong>Universal Transverse Mercator (UTM)</strong>—A grid coordinate system that projects global sections onto a flat surface to measure position in specific zones.</td>
</tr>
<tr>
<td><strong>Velocity Made Good (VMG)</strong>—The speed you are traveling in the direction of the destination.</td>
</tr>
<tr>
<td><strong>Waypoint</strong>—A specific location saved in the GPS receiver’s memory.</td>
</tr>
</tbody>
</table>
Battery Installation

The GPS 12 MAP operates on 4 AA batteries, which are installed at the base of the unit. These batteries provide up to 36 hours of use in “Power Saver” mode.

To install the batteries:

1. Remove the battery cover by turning the D-ring at the bottom of the unit 1/4 turn counter-clockwise.

2. Insert the batteries into position. Use only new batteries. Do not mix battery types (i.e., alkaline, NiCad, Lithium). The battery pole that you can still see should match the symbol (+ or -) marked on the case.

3. Replace and secure the battery cover by turning the D-ring 1/4 turn clockwise.

Battery life varies due to a variety of factors, including temperature and backlighting. You may find that lithium batteries provide longer life in colder conditions.

WARNING: Be certain that the batteries are installed correctly by observing the polarity markings on the bottom of the unit. An improperly installed battery (reversed polarity) can rupture, leaking the contents of the battery into the battery compartment.

If using rechargeable NiCad or Lithium batteries, use proper methods of disposal of used batteries. Many states and cities require environmentally sound collection and recycling of these battery types.
GETTING STARTED

Keypad Usage

- **POWER** Key turns the unit on and off, activates screen backlighting and contrast adjustment.

- **PAGE** Key scrolls through the main data pages in sequence and returns from a submenu page to a primary page.

- **MENU** Key displays a menu of options for the current page. Press twice to display the Main Menu.

- **GOTO** Key displays the GOTO page with the waypoint highlighted for GOTO operation. Pressing the GOTO key twice activates MOB (man-overboard) function.

- **ENTER/MARK** Key confirms data entry and activates highlighted fields to allow data entry. It also marks your present position.

- **QUIT** Key returns to a previous primary page, or restores a data field’s previous value.

- **IN** and **OUT** Keys increase and decrease the map scale.

- **ROCKER** Key controls the movement of the cursor and is used to select options, positions and to enter data.
The Global Positioning System (GPS) is a system of 24 satellites which circle the earth twice a day in a very precise orbit and transmit information to earth. The GPS 12 MAP must continuously “see” at least three of these satellites to calculate your position and track your movement. At times, additional satellites may be needed to determine a position.

By using an almanac (a timetable of satellite numbers and their orbits) stored in the receiver’s memory, the GPS 12 MAP can determine the distance and position of any GPS satellite and use this information to compute your position.

Your GPS receiver can only see satellites above the horizon, so it needs to know what satellites to look for. To use this almanac data, your GPS needs to be told its general location (“initialized”) or given the opportunity to find itself.

Initialization is necessary under these conditions:
• The first time you use your receiver.
• After the receiver has been moved over 500 miles from the last time you used it.
• If the receiver’s memory has been cleared and all internally stored data has been lost.

Because the GPS 12 MAP relies on satellite signals to provide you with navigation guidance, the GPS receiver’s view of the sky will generally determine how fast you get a position fix—or if you get a fix at all. GPS signals do not travel through rocks, buildings, people, metal, or heavy tree cover, so keep a clear view of the sky for best performance.

Once the GPS 12 MAP has calculated a position fix, you’ll have anywhere from five to twelve satellites in view. The receiver will select the satellites in view to update your position. If some of the satellites get blocked or “shaded,” the receiver uses an alternate satellite to maintain the position fix. A GPS receiver needs four satellites to provide a three-dimensional (3D) fix, however, it can maintain a two-dimensional (2D) fix with only three satellites. A three-dimensional fix means the unit knows its latitude, longitude, and altitude, a two-dimensional fix means the unit knows only its latitude and longitude.
**Initializing Your GPS 12 MAP**

To initialize the GPS 12 MAP, take the receiver outside and find an open area where the antenna has a clear view of the sky. You may either hold the receiver at a comfortable height with the antenna pointing up, or mount the receiver on the dash of a vehicle (Appendix B) or on a bike. (Likewise, when you use your GPS 12 MAP in a vehicle, make sure the antenna is pointing up.)

**To turn the GPS 12 MAP on, press and hold the red power key.**

The Welcome Page will be displayed while the unit conducts a self test. Once testing is complete, the Welcome Page will be replaced by a warning page, then by the Satellite Status Page. A message will inform you to “select initialization method”. (If the initialization prompt has not automatically appeared, press MENU and highlight ‘Initialize Position’.)

**To initialize your unit:**

1. Press ENTER to acknowledge the message and see a list of initialization options.

2. Use the rocker keypad to highlight 'Use Map', and press ENTER.

3. Use the rocker keypad to point the map cursor to your approximate location (within 250 miles). You may also wish to use the IN and OUT zoom keys to make it easier to identify your approximate position.

4. Press ENTER to select the position and begin searching for satellites.

This usually provides a position fix in 1 minute. You’ll know you have a fix when the unit automatically transitions from the Satellite Page to the Map Page. Your receiver is now ready to use!

**To turn the unit off:**

1. Press and hold the red power key for 1 second.
Troubleshooting

If you have trouble initializing or getting a position fix, check the following:

Does the receiver have a clear view of the sky?

If there are large buildings or mountains, or if there is heavy tree cover, the receiver may not be receiving enough satellite signals to calculate a fix. Also, if you’re using the GPS 12 MAP on a car dash, make sure the unit is placed so that it has the clearest possible view of the sky. Your GPS will only be able to detect satellites that it can “see” through your vehicle’s windshield. Depending on the slope of your dash or the overall surface area of the window, it may be necessary to mount an external antenna on your vehicle’s roof or trunk in order to give the unit a better view of the sky. (Contact your local GARMIN dealer and inquire about the GA 27 low-profile remote antenna, part number 010-10052-03.)

Have you selected the right area when initializing?

Check for the correct approximate position on the Map Page. Press PAGE until the Map Page appears, or reselect your approximate location to restart the initialization.

Have you moved more than 500 miles from the last calculated position with the receiver off?

Reinitialize the receiver by selecting your approximate position on the map, or select ‘AutoLocate’ from the Satellite Status Page options (see page 27).

To turn the GPS 12 MAP back on, press and hold the red power key.
The GPS 12 MAP features six main pages which are linked together in a chain. You can quickly scroll through the pages in either direction using the PAGE or QUIT keys. Let’s briefly tour each of these pages in order to give you some insight into how they help you navigate. We’ll go over all of them in more detail in the reference section.

Let’s start with the Satellite Status Page, which is the page you’ll view while your unit is getting a position fix. If you’re not already on this page, press PAGE or QUIT until it appears. The Satellite Status Page shows you status information that helps you understand what the receiver is doing at any given time, and it’s a page that you’ll want to occasionally refer back to as you use your unit. It features a sky view of available satellites, corresponding signal strength bars, the status of your current position fix (acquiring, 2D, 3D, etc.), and your estimated position error (EPE). You can also tell how much battery power is remaining, and you can adjust the screen contrast/backlighting by pressing the rocker keypad.

Satellites are indicated on the sky view and the signal strength bars by their corresponding number, from 01 through 32. The sky view shows where it is looking in the sky for each satellite, by indicating the direction and elevation (angle above the horizon). The signal strength bars depict the relative strength of the signal from each satellite being received. The taller the bar, the stronger the signal.

If satellite reception is lost, or an insufficient number of satellites are available, you will be alerted with a ‘Poor Coverage’ receiver status and message.
The Position Page shows you where you are, what direction you’re heading, and how fast you’re going—and it’s the page you’ll want to use when you don’t have a destination selected.

A graphic compass display at the top of the page shows your direction of travel (track) while you’re moving, while six user-selectable data fields below display your current speed, average speed, trip odometer, trip timer, and sunrise/sunset times at your current position. “User-selectable” means you can change them to display other information. We’ll cover these fields more in the reference section.

Below the user-selectable data fields are additional data fields to display your current position, along with current time and date. The current position readout can be in latitude/longitude, UTM/UPS, Maidenhead or one of several regional grids. Current time and date can be in local time or UTC (Coordinated Universal Time).

The trip odometer, trip timer and average speed readings can all be reset from the ‘Trip Computer’ option on the Main Menu. See page 70.
The Map Page shows your movement using a real-time track log (an electronic breadcrumb trail that appears directly on the map as you’re traveling), and your present position as a pointer icon in the center of the map. The Map Page also shows any nearby lakes, rivers, highways and towns. Use the zoom keys (IN and OUT) to adjust the map to the desired scale.

**To change the map scale:**

1. Press the IN zoom key to select a smaller scale and more detail for a smaller area.
2. Press the OUT zoom key to select a larger scale and display a larger area.

The map can be oriented with the top of the page always pointing north, oriented along your desired course, or it can automatically rotate to keep your current direction of travel (track) at the top of the screen. The default setting is ‘North Up’, which keeps the top of the page always pointing north.

Nearby waypoints are depicted on the map with any one of over 50 different symbols, with the waypoint name shown directly above the symbol. We’ll cover more about the GPS 12 MAP’s waypoint features and the Map Page in the reference section of this manual.
The GPS 12 MAP features two different navigation pages: Compass and Highway. The Compass Page is first. This page provides graphic steering guidance to a destination waypoint, with an emphasis on the bearing to your destination and current direction of travel. (The Highway Page places greater emphasis on the straight-line desired course and the distance and direction you are off course.) The middle of the page features a rotating ‘compass ring’ that shows your course over ground (track) while you’re moving, and a bearing pointer that indicates the direction of the destination (bearing) relative to the course over ground. The compass ring and pointer arrow work independently to show—at a glance—the direction of your movement and the direction to your destination. For instance, if the arrow points up, you are going directly to the waypoint. If the arrow points any direction other than up, turn toward the arrow until it points up—then continue in that direction.

The current speed and distance to the destination waypoint as well as the time to the destination waypoint and the current time are displayed at the top of the screen. This page provides better steering guidance than the Highway Page when travelling at slower speeds and/or when making frequent directional changes.

- Current Speed
- Distance to Waypoint
- Time to Waypoint
- Current Time
- Pointer (Bearing to Destination)
- Compass Ring

The ‘Big Numbers’ option (Compass Page Options) shows a much smaller compass display and larger data field characters. See page 40.
The GPS 12 MAP’s Highway Page also provides graphic steering guidance to a destination waypoint. As you head toward your destination, the middle of the screen provides visual guidance to your waypoint on a moving graphic “highway.” Your present position is at the bottom center of the highway display. The line down the middle of the highway represents your desired course. As you navigate toward a waypoint, the highway will actually move—indicating the direction you’re off course. To stay on course, simply move toward the center of the highway.

The top of the page indicates speed and distance to your destination (or the next waypoint in a route), along with a track compass showing current direction of travel. Next to the speed reading is the time required to reach your destination (or the next waypoint in a route), in hours/minutes or minutes/seconds. The pointer also shows the bearing to your destination, relative to your current track. If the pointer points straight ahead, you’re heading directly to your destination!

Use the Highway Page as your primary navigation page (in lieu of the Compass Page) when your main concern is following a defined course.
The GPS 12 MAP’s Main Menu provides access to additional pages (submenus) that are used to create or edit waypoints, create routes, list nearby waypoints, review trip information and timers or make changes to system settings. These six pages are divided into categories by function. The waypoint and route management features of the Main Menu are described in more detail in the Reference section of this manual. Let’s take a look at the Main Menu and one of its submenu items.

**To view the Main Menu:**

1. Press the MENU key twice.

**To select a submenu item from the Main Menu:**

1. Highlight the desired item using the rocker keypad, and press ENTER.

2. To return to the Main Menu, press QUIT.

The ‘Setup’ option provides a list of choices (presented as a series of ‘file tabs’) to perform various configuration settings including system settings, selection of position format and units of measure, time display, setting various alarms, enabling the built-in simulator feature and interface options with other equipment:

**To change units of measure for distance and speed:**

1. Select the ‘Setup’ option from the Main Menu (as described above), and press ENTER.

2. Highlight the ‘Units’ tab with the rocker keypad. The units settings are automatically displayed.

3. Highlight the ‘Distance & Speed’ field using the rocker keypad, and press ENTER. A pop-up menu appears showing the available options.

4. Select the desired option using the rocker keypad, and press ENTER.
GPS is really about marking and going to places called ‘waypoints’. Before we can use the GPS 12 MAP to guide us somewhere, we have to mark a position as a waypoint. Your GPS 12 MAP can hold up to 500 waypoints.

To mark your present position:

1. Press and hold the ENTER/MARK key. The Mark Waypoint Page will appear, with a default three-digit name for the new waypoint in the top portion of the page.

To rename the waypoint:

1. Use the keypad to highlight the name field, and press ENTER.
2. Enter the new waypoint name using the rocker keypad, and press ENTER.

Each waypoint may also be assigned a custom waypoint symbol for easy waypoint recognition on the Map Page.

To change the waypoint symbol:

1. Highlight the waypoint symbol field (immediately to the left of the waypoint name field) and press ENTER.
2. Select the desired symbol, and press ENTER.
3. Move the cursor to the ‘DONE?’ prompt, and press ENTER.

The Mark Position Page will be replaced with the page displayed before you pressed ENTER/MARK to mark your position. The new waypoint is now stored in the GPS 12 MAP’s memory.
Once you’ve stored a waypoint in memory, you can use the GPS 12 MAP to guide you to it by using the GOTO feature. A GOTO is really nothing more than a straight-line course from your present position to the destination you’ve selected. A GOTO can be performed several ways: by specifying the destination from the GOTO Page, graphically from the map display or by highlighting the waypoint name on any page (such as the Nearest Waypoints List).

**To select a GOTO destination from the GOTO Page:**

1. Press GOTO. This captures your current position as the starting point for your trip.
2. Highlight the ‘All’ tab, using the rocker keypad, to list all waypoints currently stored in memory.
3. Highlight the desired waypoint, using the rocker keypad, and press ENTER.

**To select a GOTO destination from the Map Page:**

1. With the Map Page displayed, use the rocker keypad to place the cursor over the desired destination waypoint. (If no waypoint exists at the destination location, the GPS 12 MAP will automatically create one, named ‘MAP’ in the step below.)
2. Press GOTO, and then ENTER to navigate to the selected location.

**To GOTO a listed waypoint on the Nearest Waypoints List, Nearest Cities List or Nearest Exits List:**

1. With the Nearest Waypoints List, Nearest Cities List, or Nearest Exits List displayed (see pages 49 and 50), use the rocker keypad to highlight the desired waypoint or city.
2. Press GOTO, and then ENTER to navigate to the selected location.

Once the GOTO destination is selected, use the Map Page, Compass Page and/or Highway Page to keep track of your progress as you head toward your destination.
To cancel the current GOTO destination, simply select another destination. If no destination is currently desired, or you want to resume a previously selected route, the GOTO operation may be cancelled from the GOTO Options Page.

To cancel the current GOTO destination:
1. Press GOTO.
2. Press MENU.
3. Highlight ‘Cancel GOTO’ and press ENTER.

Active Route Page

The last of the six main pages is the Active Route Page. This page shows the Active waypoint or each waypoint of a route, with waypoint name and the course along each leg (segment) of the route. When using a route, the current destination is marked with an arrow on the left-hand side of the screen. If no destination has been specified using the GOTO key or a route, no waypoints will be listed on the page. (For more information on using routes, see page 56 in the Reference section.)

Selectable Field, currently showing Distance to this Waypoint from Previous Waypoint (or start of GOTO)

Use the LEFT/RIGHT keys on the rocker keypad to select the desired data item. Available items include course, distance, fuel, and sunrise/sunset times.
The GPS 12 MAP is a powerful navigation system providing detailed mapping information in a convenient, compact package. This simulator tour is designed to show you the basic features of your new GPS 12 MAP during a simulated trip. The simulator tour assumes that the receiver has been properly initialized as outlined in the Getting Started section of this manual, and that you have not changed any of the factory default settings. If you have changed any settings (position formats, units of measure, etc.), the descriptions and pictures in the tour may not match your configuration.

Once you’re familiar with the primary functions of the GPS 12 MAP, you’ll be ready to use your new receiver on a real trip to a destination of your choice. The Reference section of this manual may be consulted for any additional questions you may have, or to learn about the more advanced features of the GPS 12 MAP. For now, let’s get started on the Simulator Tour!

If the GPS 12 MAP is currently off, we’ll need to start by turning it on.

To turn the GPS 12 MAP on, press and hold the red power key.

The Welcome Page will be displayed while the unit conducts a self test. Once testing is complete, the Welcome Page is replaced by a warning page, then by the Satellite Status Page. Since we’ll be using the simulator mode, we don’t need to wait for the receiver to acquire satellites.

**WARNING:** Keep in mind that the GPS 12 MAP does not track satellites in simulator mode and should never be used for actual navigation. The GPS 12 MAP cannot be turned on in simulator mode. If you forget to change back to normal operation before shutting the receiver off, it will automatically return to normal mode the next time you use the receiver.
To select the simulator mode:

1. Press MENU to list the options for the Satellite Status Page.
2. Highlight ‘Start Simulator’ with the rocker keypad, and press ENTER.
3. Press ENTER again to acknowledge the simulator warning message.

Let’s look at the sequence of pages again. The PAGE and QUIT keys are used to find your way around on the GPS 12 MAP.

To cycle through the main pages:

1. Press PAGE to move through each of the main pages in normal fashion.
2. Press QUIT to sequence through the main pages in reverse order.

In normal mode operation, the GPS 12 MAP would automatically sequence from Satellite Status Page to Map Page once enough satellites were received to determine your position. At that point the receiver is ready to use for navigation. Since we’re in simulator we won’t see that automatic sequence of steps, but as you cycle through the main pages, notice that the simulator imitates satellite reception and shows that information on the Satellite Status Page.

The Position Page will show the last known position as a starting location. If you’ve already initialized the receiver, as outlined in the Getting Started section, the starting location should be very close to your current position! We’ll use this starting location from which to begin our simulated trip. Let’s move on to the Map Page to see where we are, create a destination and explore the navigation features of the GPS 12 MAP.

To select the Map Page, press PAGE repeatedly until it appears.
The GPS 12 MAP’s Map Page combines digital charting with a number of user-selectable features. Before we select our destination and begin navigating toward it, let’s take a look at some of those features.

Background Roads & Railways

Nearby Waypoints

Present Position

The map display shows your present position using a pointer icon in the center of the screen. The Map Page also shows any nearby lakes, rivers, highways and towns. Use the zoom keys (IN and OUT) to adjust the map to the desired scale. The current scale is indicated in the lower-left corner.

To change the map scale:

1. Press the IN zoom key to select a smaller scale and display a smaller geographic area.

2. Press the OUT zoom key to select a larger scale and display a larger geographic area.

The map can be oriented with the top of the page always pointing north (‘North Up’), oriented along your desired course (‘Course Up’), or it can automatically rotate to keep your current direction of travel at the top of the screen (‘Track Up’).

Nearby waypoints are depicted on the map with any one of over 50 different symbols, with the waypoint name displayed directly above the symbol. Let’s create a waypoint directly on the map display to see how that process works, then we’ll navigate to this new waypoint.
Select a five mile scale by pressing zoom IN or OUT repeatedly.

Working from the Map Page is a simple process that centers on the use of a reference “arrow”. Controlled by the rocker keypad, the reference arrow is an important tool allowing you to pan to other areas on the map display, create waypoints, view waypoint information and create routes. To get a feel for using the Map Page and the arrow, try the following exercise:

1. Using the rocker keypad to move the arrow, try following a highway (or other feature) near your position. Simply press and hold one side of the rocker keypad to move more quickly. Notice how a data field appears above the map, showing the bearing and distance from present position to the cursor, along with the latitude/longitude of the arrow’s position.

2. Using the rocker keypad, move the arrow in any direction until you find a nearby city or town. Once you find a nearby city or town, place the pointer on it to highlight the location. Now, press ENTER to create a waypoint at the arrow location and display the New Map Waypoint Page.

3. If the name of the city or town is longer than six characters, the GPS 12 MAP will abbreviate the name when it creates the waypoint. (If you select an open location on the map, where no city, town or other feature is located, a three-digit number is pre-assigned to the new waypoint created at the panning arrow location. To change the name, highlight the waypoint name field, press ENTER and use the rocker keypad to enter a new name – UP/DOWN to change the first character, RIGHT to move to the next character, and repeat. Once the new name is spelled out, press ENTER.)
4. A city symbol is assigned to the new waypoint, but let’s use a special symbol to identify it. Highlight the waypoint symbol field, using the rocker keypad, and press ENTER. Use UP/DOWN on the rocker keypad to select the ‘Information’ icon (‘?’) and press ENTER.

5. To save the new waypoint, highlight ‘Done’ with the rocker keypad and press ENTER.

Now that we’ve created our new waypoint, let’s see how the GPS 12 MAP is used to navigate to it. The reference arrow can also be used to GOTO any point on the map—even without a waypoint already at that location—by simply pressing GOTO. (We won’t try that here. A waypoint named ‘MAP’ is automatically created, so all the previous steps for creating and naming a waypoint wouldn’t be needed. You might want to experiment with this procedure at the end of the Simulator Tour.) For the Simulator Tour, we’ll stick with the waypoint we just created.

To select the GOTO destination:

1. Press GOTO.

2. If the ‘All’ file tab is not selected, use the rocker keypad to highlight this tab. (‘All’ will display a list of all waypoints currently stored in memory.)

3. Highlight the new waypoint you just created using the rocker keypad, and press ENTER.

Notice that a course line appears on the map display showing the way to our destination. Imagine you’re about to depart. Maybe you’re heading out from the marina or you’re about to venture into the wilderness. What if you want to return to your present position when you’re done for the day? You have two options available:

- You can mark your present position now and save it as a waypoint, or
- You can use the TracBack feature at the end of the day to retrace your steps—following the same path you travelled, but in reverse.

For now, we’ll mark our present position and save it as a waypoint. (You might want to experiment with the TracBack feature later. It’s described on page 54.)
To mark your present position:

1. Press and hold the ENTER/MARK key. The Mark Waypoint Page will appear, with a default three-digit name for the new waypoint in the upper-left portion of the page.

Let’s call our present position ‘HOME’. (If you were at home when you initialized your GPS 12 MAP, you might want to keep this waypoint in memory for future use!)

To rename the waypoint and change its symbol:

1. Use the keypad to highlight the name field, and press ENTER.
2. Enter the new waypoint name (‘HOME’) using the rocker keypad, and press ENTER. (Remember to use UP/DOWN to change the character and RIGHT to move to the next character field.)
3. Highlight the waypoint symbol field and press ENTER.
4. Select the ‘Residence’ symbol, and press ENTER.
5. Move the cursor to the ‘DONE?’ prompt, and press ENTER.

Now we have two waypoints in memory and on the map: the city location we saved earlier and ‘HOME’. It’s about time we get started, so let’s plug a speed into the simulator to animate the displays!

To enter a simulated speed and animate the displays:

1. Press PAGE repeatedly until the Compass Page appears.
2. Enter a simulated speed of ‘30’ (mph or knots) using the rocker keypad. (Press UP on the rocker keypad once to select ‘30’. The speed readout is on the upper left corner of the Compass Page.)
3. Press PAGE (or QUIT) repeatedly to return to the Map Page.
Notice the information on the map display is slowly moving? That’s how it would look in actual use as well. The background map information and nearby waypoints will move across the screen, while your current position remains fixed in the center.

The other primary navigation screens are the Compass and Highway pages, with the Compass Page appearing first in the sequence of main pages.

**To view the Compass Page, press PAGE.**

The GPS 12 MAP’s Compass Page provides graphic steering guidance to a destination waypoint. The middle of the page features a rotating ‘compass ring’ that shows your course over ground (track) while you’re moving, and a bearing pointer that indicates the direction of the destination (bearing) relative to the course over ground. The compass ring and pointer arrow work independently to show—at a glance—the direction of your movement and the direction to your destination. If the arrow points up, you are going directly to the waypoint. If the arrow points any direction other than up, turn toward the arrow until it points up—then continue in that direction. The distance to the next waypoint, time to the next waypoint and current speed are displayed to the right of the graphic compass display. To see how all this works on our simulated trip, let’s head off course and watch the displays change.

To move off course / on course in simulator mode, use the LEFT/RIGHT keys on the rocker keypad.
To view the Highway Page, press PAGE.

The Highway Page provides a graphic highway display that shows your movement relative to the desired course. The line down the middle of the highway represents your desired course. As you navigate toward your destination, the highway will actually move, indicating the direction you’re off course. To stay on course, simply steer toward the center of the highway. As you approach the waypoint, the highway will end at the final destination. When the waypoint marker is at the bottom center of the highway display, you’ve arrived at your destination. A track compass also shows your current track directly above the highway display, making it easy to see at a glance which way you’re headed.

The pointer arrow at the top of the page indicates the direction to the destination waypoint (bearing) relative to the direction you are moving (track). If the pointer points straight ahead, you’re heading directly to the waypoint. If not, turn in the direction of the pointer and the pointer will swing around, pointing straight ahead as you begin moving toward the destination waypoint. Try moving on course/ off course again using the rocker keypad and watch as the highway display and bearing pointer change.

That’s it! You’ve covered the basics and you’re ready to venture off on your own. Operating the GPS 12 MAP is just as simple as you’ve seen here in the Simulator Tour, but in real applications you won’t need to change speed and track with the rocker keypad. That’s all done automatically utilizing information from the GPS satellites as you move about.

Before ending the tour, try a few experiments of your own, such as going back to the ‘HOME’ waypoint, retracing your steps utilizing the TracBack feature, or creating a few more waypoints. Use the Reference section of this manual for more ideas.

To end the Simulator Tour, turn the GPS 12 MAP off, press and hold the red power key.
The GPS 12 MAP’s Satellite Status Page provides a visual reference of various receiver functions, including current satellite coverage, receiver operating mode, battery level and position accuracy. As the receiver locks onto satellites, a signal strength bar will appear for each satellite in view, with the appropriate satellite number (01-32) underneath each bar. The progress of satellite acquisition is shown in three stages:

- No signal strength bars— the receiver is looking for the satellites indicated.
- Hollow signal strength bars— the receiver has found the satellite(s) and is collecting data.
- Solid signal strength bars— the receiver has collected the necessary data and the satellite(s) is ready for use.

Each satellite has a 30-second data transmission that must be collected (hollow bar status) before that satellite may be used for navigation (solid bar status). Once a fix has been calculated, the GPS 12 MAP will then update your position, track, and speed by selecting and using the best satellites in view. You can also access the GPS 12 MAP’s backlight and contrast feature from this or any main page.

**To adjust the screen contrast and/or backlighting:**

1. Press LEFT or RIGHT on the rocker keypad to adjust the level of contrast, and press ENTER to save the new contrast setting.

2. Press UP or DOWN on the rocker keypad to adjust the level of backlighting, and press ENTER to save the new backlight setting.

**Sky View and Signal Strength Bars**

The sky view and signal strength bars give you an indication of what satellites are visible to the receiver, whether or not they are being used to calculate a position fix, and the signal quality. The satellite sky view shows a bird’s-eye view of the position of each available satellite relative to the unit’s last known position. The outer circle represents the horizon (north up); the inner circle 45º above the horizon; and the center point directly overhead.
You can use the sky view to help determine if any satellites are being blocked, and whether you have a current position fix (indicated by a ‘2D Navigation’ or ‘3D Navigation’ in the status field). You can also set the sky view to a ‘Track Up’ configuration, causing the top of the sky view to align along your current track heading.

When the receiver is looking for a particular satellite, the corresponding signal strength bar will be blank and the sky view indicator will not be highlighted. Once the receiver has found the satellite, a hollow signal strength bar will appear, indicating that the satellite has been found and the receiver is collecting data from it. The satellite number in the sky view will appear highlighted. As soon as the GPS 12 MAP has collected the necessary data to calculate a fix, the status field will indicate a 2D or 3D status. (For ‘2D’, you may need to enter your altitude. See page 27.)

**Receiver Status**

Receiver status is indicated at the top of the page. The status will be shown as one of the following conditions:

**Searching** — the GPS 12 MAP is looking for any available satellites in view.

**AutoLocate** — the GPS 12 MAP is initializing and collecting new almanac data. This process can take up to 5 minutes, depending on the satellites currently in view.

**Acquiring** — the receiver is collecting data from available satellites, but has not collected enough data to calculate a position fix.

**2D Navigation** — at least three satellites with good geometry have been locked onto and a 2-dimensional position fix (latitude and longitude) is being calculated. ‘2D Diff’ will appear when you are receiving DGPS corrections in 2D mode.

**3D Navigation** — at least four satellites with good geometry have been locked onto, and your position is now being calculated in latitude, longitude and altitude. ‘3D Diff’ will appear when you are receiving DGPS corrections in 3D mode.
**Poor GPS Coverage**— the receiver isn’t tracking enough satellites for a 2D or 3D fix due to bad satellite geometry.

**Not Usable**— the receiver is unusable, possibly due to incorrect initialization or abnormal satellite conditions. Turn the unit off and back on to reset, and reinitialize the receiver if necessary.

**Simulating Nav**— the receiver is in simulator mode.

**‘Need to Select Initialization’ Prompt**

If no satellites are received for several minutes (or an insufficient number of satellites are received to determine a position fix) a message will appear, prompting you to initialize the receiver (see page 3). This allows you to specify a starting location from which to search for satellites, or to enable the AutoLocate feature, and is useful if you have traveled over 500 miles with the receiver off. (This message will automatically appear when you first use your GPS 12 MAP. The prompt may also appear during normal use if the antenna is shaded or the unit is used indoors.)

**Battery Level Indicator**

The Satellite Status Page also features a battery level indicator, located to the left of the sky view, which displays the strength of the unit’s batteries. The battery indicator will not appear if the receiver is operating on external power.

**NOTE:** The battery level indicator is calibrated for alkaline batteries. NiCad and lithium batteries will display the battery level differently due to voltage differences. To display battery level accurately select the appropriate type, as described on page 73. The GPS 12 MAP features an internal 10-year lithium battery that will maintain the unit’s memory when the receiver is not running off batteries or external power.
The Satellite Status Page also indicates the accuracy of the position fix, using Estimated Position Error (EPE) and Dilution of Precision (DOP) figures. DOP measures satellite geometry quality (i.e., number of satellites received and where they are relative to each other) on a scale from one to ten. The lowest numbers are the best accuracy and the highest numbers are the worst. EPE uses DOP and other factors to calculate a horizontal position error, in feet or meters.

Satellite Status Page Options

Many features of the GPS 12 MAP are menu driven. Each of the main pages has an options menu, allowing you to customize the corresponding page to your preferences and/or select special features which specifically relate to that page.

To display the Satellite Status Page Options, press MENU (with the Satellite Status Page displayed).

The following Satellite Status Page options are available:

- **Start Simulator**—allows you to activate the GPS 12 MAP’s built-in simulator mode. If ‘Start Simulator’ is selected, ‘Stop Simulator’ will appear as an option instead.

  **To activate (deactivate) simulator mode:**
  
  1. Highlight ‘Start Simulator’ (or ‘Stop Simulator’) and press ENTER.
  
  2. Highlight ‘Yes’ and press ENTER.

- **Track Up**—changes the sky view display from ‘North Up’ orientation to align to current direction of travel (track). If ‘Track Up’ is selected, ‘North Up’ will appear as an option instead.

  **To change the sky view orientation:**
  
  1. Highlight ‘Track Up’ (or ‘North Up’) and press ENTER.
**AutoLocate**—forces the GPS 12 MAP to search for any available satellite(s) to determine its position. This option is useful if you’ve relocated a long distance (>500 miles) from the last location the GPS 12 MAP was used.

**To select AutoLocate, highlight** *AutoLocate* **and press ENTER.**

**Initialize Position**—allows you to designate your approximate position in order to speed up satellite acquisition. This option may be used in lieu of ‘AutoLocate’, above.

**To initialize your starting position:**

1. Highlight ‘Initialize Position’ and press ENTER.
2. Designate your approximate position on the map using the rocker keypad and press ENTER. (You may wish to use the IN/OUT zoom keys to adjust the level of detail displayed, as you determine your approximate position.)

**Set 2D Altitude**—allows you to designate your approximate altitude, when the GPS 12 MAP is acquiring satellites or navigating in 2D mode. By default, 2D navigation will attempt to use the last known altitude. If the altitude shown is off by several hundred feet (or more), manually entering your approximate altitude will enable the receiver to more accurately determine a position fix.

**NOTE:** You can only enter altitude while in 2D or in ‘Simulator’ mode. Altitude is automatically calculated in 3D Mode.

**To enter an altitude:**

1. Highlight ‘Set 2D Altitude’ and press ENTER.
2. Enter your approximate altitude using the rocker keypad, and press ENTER.
Contrast and Backlighting

On page 23, we introduced display contrast and backlighting adjustments accessible from the Satellite Status Page. Display settings can also be adjusted from any page, by pressing the red power key. When backlighting is on, a bulb icon will appear on the Satellite Status Page, to the bottom left of the sky view. To adjust the duration of the screen backlighting, refer to the operation setup section (see page 73).

To adjust the screen contrast and/or backlighting from any page:

1. Press the red power key momentarily. A window will appear showing the current contrast and backlighting settings.
2. Press LEFT or RIGHT on the rocker keypad to adjust the level of contrast, and press ENTER to save the new contrast setting.
3. Press UP or DOWN on the rocker keypad to adjust the level of backlighting, and press ENTER to save the new backlight setting. Press POWER to return to the last-used setting.

Position Page

The second page in the GPS 12 MAP’s main page sequence is the Position Page. This page shows you where you are, what direction you’re heading, and how fast you’re going, and it’s most useful when you are traveling without an active destination waypoint. The graphic heading display at the top of the page indicates the direction you’re heading, or track, only while you’re moving.

Directly below this display are the speed, average speed, trip timer, trip odometer and sunrise/sunset fields (default). The sunrise/sunset times indicated are for your present position. These times, and the current time display at the bottom of the page, can be displayed in local or UTC (universal) time. The lower part of the page shows your current latitude and longitude in degrees and minutes (default). The GPS 12 MAP uses this basic information to mark exact positions as waypoints, which help guide you from one place to another. Average speed, sunrise and
sunset times (at your present position) also appear on the Position Page (as default selections). Units of measure and the position readout are selectable from the Main Menu, as outlined on page 74. ‘Trip Computer’ functions—such as average speed, max speed, trip odometer and trip timer—can each be reset from the Main Menu, as described on page 70.

Many features of the GPS 12 MAP are menu driven. Each of the main pages has an options menu, allowing you to custom tailor the corresponding page to your preferences and/or select special features which specifically relate to that page.

To display the Position Page Options, press MENU (with the Position Page displayed).

The following options are available:

**Average Position**—allows you to average position samples over time and save the averaged result as a waypoint. Averaging reduces the effects of selective availability on position error and results in a more accurate position reading.

**To average position samples and save the result as a waypoint:**


2. When the ‘Estimated Accuracy’ and/or ‘Measurement Count’ figures reach the desired value(s), highlight ‘Save’ and press ENTER. (To cancel the averaging function, highlight ‘Discard’ and press ENTER.)

3. The New Waypoint Page appears with a three-digit number assigned as a name for the new waypoint. To save the waypoint with this name, highlight ‘Done’ and press ENTER. Or,

4. To change the waypoint name, highlight the waypoint name field and press ENTER. Use the rocker keypad to enter a new name for this waypoint and press ENTER when finished. Highlight ‘Done’ and press ENTER to save the waypoint.
**Change Fields**— allows you to choose the data displayed on the six user-selectable data fields. Available data types are: Altitude, Average (Avg) Speed, Battery (Bat) Timer, Max Speed, Odometer, Speed, Sunrise (at present position), Sunset (at present position), Track, Trip Odometer, Trip Timer, User Timer and Voltage. See page vii for descriptions of navigation terms.

**To change a data field:**

1. Highlight ‘Change Fields’ and press ENTER.
2. Highlight the data field you wish to change (using the rocker keypad) and press ENTER.
3. Select the type of data you want to appear on this field and press ENTER.

**Restore Defaults**— resets all data fields to the factory default settings.

**To restore the factory default settings,**

highlight ‘Restore Defaults’ and press ENTER.

The GPS 12 MAP features a powerful real-time moving map that can do much more than just plot your course and route. The Map Page also displays background detail, including geographic names, lakes, rivers, coastlines and highways. You can load maps with detailed information for specific geographical areas. (See MapSource Info on page 36) An on-screen cursor lets you pan ahead to nearby waypoints, determine the distance and bearing to any map position, mark new waypoints while you navigate or retrieve exit information. The GPS 12 MAP also features dedicated zoom keys for instant zooming (see page 2). The map portion of the page displays your present position as a pointer icon, with your track and/or route displayed as small points on the screen (an electronic bread crumb trail, if you will). Nearby waypoints are represented with names and symbols. You may select which features are shown via the Map Page Options (see pg. 35).

The data window above the map displays the time and distance to next waypoint, plus your current speed (all defaults). A bearing pointer lets you know if you’re heading toward your destination. (If the pointer points straight ahead, you’re heading directly to it.) Each data field may be configured to display any one of twenty-four data options.
Zooming and Panning

There are three main functions you can perform from the Map Page: zooming, panning, and pointing. The map has 24 map scales (from 120 feet to 500 miles, or 30 meters to 800 km) which are selected by pressing the IN and OUT zoom keys. The current map scale is indicated in the bottom left corner of the map display.

To change the map scale:

1. Press zoom IN to see a smaller area with more detail.
2. Press zoom OUT to see a larger area with less detail.

Another function on the Map Page is the pan function, which allows you to move the map with the keypad in order to view areas beyond the current map.

To activate the pan function:

1. Use the rocker keypad to move the map in any direction, including diagonally.

As you begin to pan on the map, an arrow appears. This arrow will serve as a target marker for the map. When the arrow is placed on an object, the name of that object will be highlighted. (If the name wasn’t originally displayed it will appear when the arrow is placed on the object.) This feature applies to waypoints, roads, lakes, rivers—pretty much everything displayed except route lines and track log data.

When a waypoint name is highlighted, you can review information about the waypoint, list waypoint options, or execute a GOTO right from the Map Page.
To select an on-screen waypoint with the panning arrow:

1. Use the rocker keypad to highlight the desired waypoint.
2. Press ENTER to review information for the selected waypoint.
3. To exit the information page, press QUIT.

To GOTO a highlighted waypoint:

1. With the waypoint highlighted, press GOTO, followed by ENTER.

The GOTO function can be used anywhere on the map. If a waypoint or highway exit is not highlighted, a new waypoint (called ‘MAP’) will be created at the arrow location before the GOTO is initiated. If want to save this waypoint, rename it, as the next ‘MAP’ waypoint entered will override the current one.

To cancel the pan function and re-center the map on your position:

1. Press the QUIT key.

Highway exit information is also available when using the pan function. Simply place the panning pointer over the exit location to retrieve additional information—including available services—about the exit. Exit information is generally limited to interstate highways and is categorized into two types:

- **Common Exits**— traditional ramp, cloverleaf or intersection exits.
- **Special Exits**— rest areas, service areas, toll booths, welcome centers and weigh stations.

Common exits are depicted with an open square icon when services are available and a filled-gray square icon when no services are available.
To display available services for an exit shown on the map page:

1. Use the rocker keypad to place the panning arrow on the desired exit. A window will appear showing the exit number, along with icons depicting the available services.

2. Press ENTER to display the Exit Info Page for the selected exit. The Exit Info Page shows the number of available services, and the bearing and distance to the exit location.

3. Highlight the “View” button at the bottom of the page and press ENTER to display the Services Near Exit List. The Services Near Exit List shows a service icon and the name for each available service.

4. Highlight the desired service and press ENTER to display an Exit Service Detail Page. This page provides a checklist of available services—such as fuels, parking, convenience stores, etc.

5. Press QUIT, as often as needed, to back out of each exit services page. If you continue to press QUIT, you will return to the Map Page.

Many features of the GPS 12 MAP are menu driven. Options menus are available from the exit services pages, allowing you to select special features which specifically relate to that page. These include options to save highway exit locations as waypoints and a setup feature to exclude those services you don’t wish to view.

Show Map—allows you to return to the map, centered on the selected exit. While viewing the map display, you can also use the IN and OUT zoom keys to see additional detail.

To view the map area around an exit on the Exit Info Page:

1. Select ‘Show Map’ (from the Exit Info Page Options) and press ENTER.
Save As Waypoint—creates a waypoint at the exit location and saves it in memory. If the exit name is longer than six characters, it will be abbreviated when creating the waypoint.

To save an exit location as a waypoint:

1. Select 'Save As Waypoint' (from the Exit Info Page Options) and press ENTER.

2. With 'Done' highlighted, press ENTER to save the new waypoint.

Services Setup—allows you to designate which service types you wish to display on the exit services pages. Those service types which you disable will not be included in the number of available services (on the Exit Info Page) or in the Services Near Exit List.

To designate the service types you want to appear on the exit services pages:

1. Select 'Services Setup' (from the Services Near Exit List Options) and press ENTER.

2. Use the rocker keypad to select the desired service type and press ENTER to toggle between enabled (denoted by an "X") or disabled.

Restore Defaults—resets all options to the factory default settings.

To restore the factory default settings, highlight 'Restore Defaults' (from any exit services page option window) and press ENTER.
Many GPS 12 MAP features are menu driven. Each of the main pages has an options menu, allowing you to custom tailor the corresponding page to your preferences and/or select special features which specifically relate to that page.

**To display the Map Page Options, press MENU (with the Map Page displayed).**

The following options are available:

- **Data Fields Off**—allows you to select between a full-screen map display or the default map display with data window. If the data fields are off, ‘Data Fields On’ will appear as an option instead.

- **To turn the data fields off (or on), highlight ‘Data Fields Off’ (or ‘Data Fields On’) and press ENTER.**

- **Change Fields**—allows you to choose the data displayed on four user-selectable data fields. There are twenty-four available data types, including Average (AVG) Speed, Bearing, Distance, ETA to Destination (DEST), Speed, Time to Destination (DEST), Track and a Trip Odometer. See page vi for descriptions of navigation terms.

- **To change a data field:**
  1. Highlight ‘Change Fields’ and press ENTER.
  2. Highlight the data field you wish to change and press ENTER.
  3. Select the type of data you want to appear on this field and press ENTER.
**MapSource Info** — shows the number of maps downloaded from the optional MapSource software package and the amount of memory used (in kilobytes). MapSource allows you to supplement the built-in map with additional detail, including residential streets. Each downloaded map is described by name, and may be deselected if you wish to retain the map in memory, but not display the data on the Map Page. (When a MapSource file is selected, the boundary for any downloaded map is shown on the Map Page as a gray shaded outline.)

**To display the MapSource Info Page:**

1. Highlight ‘MapSource Info’ and press ENTER.
2. Use the rocker keypad to scroll through the list of downloaded maps.
3. To select/deselect a map, highlight the box to the immediate left of the desired map. Press ENTER to select/deselect the map. The map is selected and will be displayed on the Map Page when an ‘X’ appears in the box adjacent to that map.

**Measure Dist** — allows you to measure the bearing and distance between any two points on the map display.

**To measure bearing and distance between two points:**

1. Highlight ‘Measure Dist’ and press ENTER. An on-screen pointer will appear on the map display at your present position.
2. Move the cursor to the desired reference point (the point you want to measure from) and press ENTER.
3. Move the cursor to the point you want to measure to. The bearing and distance from the reference point will be displayed at the top of the page.

**Restore Defaults** — resets all data fields to the factory default settings.

**To restore the factory default settings,** highlight ‘Restore Defaults’ and press ENTER.
**Map Setup** — allows you to configure the map display to your preferences, including map detail, map orientation, automatic zoom, lat/lon grid, track and route lines, exits and waypoint names. The map setup option uses a ‘file tab’ feature, making it easier to organize the various settings and easier for you to use. The following section lists the file tabs and the settings available under each tab.

- **Map** - Detail, Orientation, AutoZoom, Accuracy Circle.
- **Source** - Built-in Base Map, MapSource Files
- **Line** - Track Log, Active Route Lines, Roads/Street Labels
- **Pnts** - All Waypoints and Text, Active Route Wpts, Common Exits and Special Exits
- **City** - Large/Medium/Small Cities, Small Towns, Text
- **Geo** - Geo Points, Rivers, Lakes, Park Areas
- **Topo** - Major Contour, Med. Contour, Min. Contour, Land Cover
- **Other** - Marine Navaids, Lat/Lon Grid, Metro Areas, Railroads

**NOTE:** Large cities are those with approximate populations greater than 200,000. Medium cities are those greater than 50,000 and Small cities are those greater than 5,000. Small towns have populations under 5,000 or the population is unknown.

To change a map setup feature:

1. Highlight ‘Map Setup’ and press ENTER.
2. To set the desired map detail, select the ‘Map’ tab (if not already selected). Scroll down (using the rocker keypad) to highlight the ‘Detail’ field and press ENTER. Select the desired detail level - More, Normal, Less, Least and press ENTER

**NOTE:** The ‘Detail’ setting applies to any map feature set to “Auto”. These features for which you have specified a maximum scale, or turned “Off”, are unaffected by the detail setting.
3. To change map orientation, select the 'Map' tab (if not already selected). Scroll down to highlight the 'Orientation' field and press ENTER. Select 'North Up' to fix the top of the map display to a north heading. Select 'Track Up' to adjust the top of the map display to your current track heading. Select 'Course Up' to fix the top of the map display to your desired course. Press ENTER to accept the selected option.

4. To enable/disable automatic zoom, select the 'Map' tab (if not already selected). Scroll down to highlight the 'Auto Zoom' field and press ENTER. Select 'On' or 'Off' to enable or disable automatic zoom. Press ENTER to accept the selected option. The automatic zoom feature will automatically adjust the map scale from 80 miles through each lower scale, stopping at 800 ft as you approach your destination waypoint.

5. To enable/disable the accuracy circle, select the 'Map' tab (if not already selected). Scroll down to highlight the 'Acc. Circle' field and press ENTER. Select 'On' or 'Off' to enable or disable the accuracy circle. Press ENTER to accept selected option. With the accuracy circle on, a gray circle will appear around your position (at lower scale settings) depicting the estimated accuracy of your position reading.

6. To enable/disable the built-in base map or MapSource files, select the 'Source' tab. Scroll down to highlight 'Basemap' or 'MapSource' and press ENTER. Select 'On' or 'Off' to enable or disable the selected map data and press ENTER.

7. For all waypoints, active route waypoints, rivers/lakes and cities: select the appropriate tab. Scroll down to highlight the zoom field for the desired feature and press ENTER. Select the maximum scale at which the feature should appear on screen, or 'Off' to never display, and press ENTER. Highlight the text field for the desired feature and press ENTER. Select the text size for the desired feature, or 'None' to disable text, and press ENTER.

8. For track log data, active route lines, local roads, street labels, highway exits, lat/lon grid, metro areas, and railroad lines: select the appropriate tab. Scroll down to highlight the zoom field for the desired feature and press ENTER. Select the maximum scale at which the feature should appear on screen, or select 'Off' to never display the feature. Press ENTER to accept the settings.
Whenever a destination waypoint(s) has been selected, the GPS 12 MAP’s Compass Page will guide you to your destination with digital readouts and a graphic compass display, which includes a bearing pointer. Use this page (instead of the Highway Page) when travelling at slower speeds, when making frequent directional changes, or where straight line navigation is not possible due to obstructions or terrain.

The middle of the page features a rotating ‘compass ring’ that shows your course over ground (track) while you’re moving. (Your present course over ground is indicated at the top of the compass ring.) A bearing pointer, in the middle of the compass ring, indicates the direction of the destination (bearing) relative to the course over ground. The compass ring and pointer arrow work independently to show—at a glance—the direction of your movement and the direction to your destination. For instance, if the arrow points up, you are going directly to the waypoint. If the arrow points any direction other than up, turn toward the arrow until it points up—then continue in that direction.

At the top of the page are four user-selectable data fields that display current speed, distance and time to next waypoint, and current time (defaults). Each data field may be configured to display any one of twenty-five data options.
To display the Compass Page Options, press MENU (with the Compass Page displayed).

The following options are available:

**Big Numbers**— allows you to select a different Compass Page layout, with a smaller compass display and two user-selectable, large-character data fields. If ‘Big Numbers’ is selected, ‘Big Compass’ will appear as an option instead.

To toggle between Compass Page formats, highlight ‘Big Numbers’ (or ‘Big Compass’) and press ENTER.

**Change Fields**— allows you to choose the data displayed on four user-selectable data fields (two fields for the ‘Big Numbers’ option). There are twenty-five available data types, including Average (AVG) Speed, Bearing, Distance (DIST) to Destination, ETA to Destination (DEST), Speed, Time to Destination (DEST), Track, and a Trip Odometer. See page vi for descriptions of data terms.

To change a data field:

1. Highlight ‘Change Fields’ and press ENTER.
2. Highlight the data field you wish to change and press ENTER.
3. Select the type of data you want to appear on this field and press ENTER.

**Restore Defaults**— resets all data fields to the factory default settings.

To restore the factory default settings, highlight ‘Restore Defaults’ and press ENTER.
The GPS 12 MAP's Highway Page also provides graphic steering guidance to your destination, by using a graphic highway display. At the top of the page are four user-selectable data fields that display current speed, distance and time to next waypoint, and a bearing pointer (defaults). The bearing pointer always points to the destination waypoint (or the next waypoint when using a route) relative to the direction you are moving (track). If the bearing pointer points straight ahead, you are heading directly to your destination. If the bearing pointer points any direction other than up, turn toward the arrow until it points up—then continue in that direction. Each data field may be configured to display any one of twenty-three data options.

The graphic heading compass beneath the data fields indicates the direction you are moving (track). Directly below the heading compass, the highway display provides visual guidance to the destination waypoint and keeps you on your intended course line. Your course is represented by the center line down the middle of the graphic highway. As you head toward your destination, the highway perspective will move to indicate your progress to the waypoint and which direction you should steer to stay on course. When you are navigating a route, the highway display will show each route waypoint in sequence, with the route course indicated by a black highway. Nearby waypoints not in the route will also be displayed. You can zoom in or out on the highway display for a smaller or larger view. Five available settings range from 1X to 16X, with a default setting of 8X.

**To zoom in or out on the highway display:**

1. Press the IN zoom key to increase the zoom level and show a smaller view area.
2. Press the OUT zoom key to decrease the zoom level and show a larger view area.
To display the Highway Page Options, press MENU (with the Highway Page displayed).

The following options are available:

**Sign Posts Off**—removes the waypoint markers from the highway display. If ‘Sign Posts Off’ is selected, ‘Sign Posts On’ will appear as an option instead.

**To remove (or display) waypoint markers on the highway, highlight ‘Sign Posts Off’ (or ‘Sign Posts On’) and press ENTER.**

**Change Fields**—allows you to choose the data displayed on four user-selectable data fields. There are twenty-three available data types, including Average (AVG) Speed, Bearing, Distance (DIST) to Destination, ETA to Destination (DEST), Speed, Time to Destination (DEST), Track, a Trip Odometer and a bearing Pointer. See page vi for data type descriptions.

**To change a data field:**

1. Highlight ‘Change Fields’ and press ENTER.
2. Highlight the data field you wish to change and press ENTER.
3. Select the type of data you want to appear on this field and press ENTER.

**Restore Defaults**—resets all data fields to the factory default settings.

**To restore the factory default settings, highlight ‘Restore Defaults’ and press ENTER.**
The GPS 12 MAP stores up to 500 waypoints, with a selectable symbol and comment available for each waypoint. Waypoints can be created using five methods:

**Mark Present Position** — your present position can be captured and saved as a waypoint using the ENTER/MARK key.

**On Map** — a new waypoint position can be created directly on the map display using the panning arrow.

**Text Entry** — waypoints can be created by entering position coordinates manually (from a chart, etc.) or by referencing bearing and distance from a previously stored waypoint (or present position).

**Average Position** — position samples can be averaged over time and the result saved as a waypoint. Averaging reduces the effects of selective availability and improves the accuracy of the position reading. (See page 29 for more info.)

**Nearest Locations** — nearest cities or highway exits can be saved as waypoints from the nearest locations pages. (See page 49 for more info.)

**Marking Present Position**

The GPS 12 MAP’s mark feature lets you quickly capture your present position in order to create a new waypoint. You must be locked onto satellites, with a valid position fix, to mark your present position.

**To mark your present position:**

1. Press and hold the ENTER/MARK key. The Mark Waypoint Page is automatically displayed.

2. To change the waypoint name (a three-digit number is automatically assigned), highlight the waypoint name field and press ENTER. Use the rocker keypad to enter the new waypoint name and press ENTER when finished.

3. To save the waypoint in memory, highlight ‘Done’ and press ENTER.

The ENTER/MARK key allows you to mark your current position as a waypoint. You can give this waypoint any name you choose; up to six characters.
Creating Waypoints

User waypoints can also be created by entering the position coordinates for the waypoint.

Marking Waypoints on the Map Page

Waypoints can also be quickly created from the Map Page, which allows you to “point and shoot” at any map position to create a new waypoint.

To create a new waypoint on the map:

1. Press the PAGE key repeatedly to select the Map Page.
2. Use the rocker keypad to move the arrow to the desired map position. You may also need to use the IN and OUT zoom keys, in conjunction with the rocker keypad, to speed up this process.
3. Press ENTER to capture the arrow position and display the New Waypoint Page. (If the arrow is placed on a highway exit, the exit services pages will appear instead. To create a waypoint at a highway exit location, see page 34.)
4. To change the waypoint name (a three-digit number is automatically assigned), highlight the waypoint name field and press ENTER. Use the rocker keypad to enter the new waypoint name and press ENTER when finished.
5. To save the waypoint in memory, highlight ‘Done’ and press ENTER.

Creating Waypoints by Text Entry

Waypoints may be created by manually entering the position coordinates or by entering the bearing and distance from an existing waypoint (or present position).

To create a new waypoint by manually entering its coordinates, or by bearing/distance from another position:

1. Press the MENU key twice to select the Main Menu.
2. Highlight ‘Waypoints’ and press ENTER. A list of all waypoints stored in memory is displayed.
3. Press MENU to display the Waypoint List Options.

5. To enter a name for the new waypoint, highlight the waypoint name field and press ENTER. Use the rocker keypad to enter the waypoint name and press ENTER when finished.

6. To enter position coordinates for the new waypoint, highlight the waypoint coordinates field and press ENTER. Use the rocker keypad to enter the position coordinates and press ENTER when finished. (For lat/long coordinates, enter both the latitude and longitude information before pressing ENTER.) OR,

7. To create the new waypoint by referencing another position, highlight the reference waypoint name field and press ENTER. Use the rocker keypad to enter the name of the reference waypoint and press ENTER. (If the reference waypoint name field is left blank, your present position will be used as the reference position.) Use the same procedure to enter the bearing (BRG) and distance (DIST) from the reference waypoint to the new waypoint. (Remember to press ENTER once each data item is selected with the rocker keypad.) OR,

8. To save the new waypoint in memory, highlight ‘Done’ and press ENTER.

**Waypoint List Options**

The Waypoint List Options were displayed using the first three steps, above. In addition to ‘New Waypoint’, there are five additional options:

- **Show Map**—allows you to view the map area around the highlighted waypoint on the Waypoint List. While viewing the map display, you can also use the IN and OUT zoom keys to see additional detail.

**To view the map area around a highlighted waypoint on the Waypoint List:**

1. Select ‘Show Map’ (from the Waypoint List Options) and press ENTER.

- **Spell ’n Find**—allows you to display the Waypoint Edit Page for any waypoint in memory, by typing in the first few characters of the waypoint’s name.

You can choose from a list of symbols used to identify the waypoint on the map display.

The Spell ’n Find option allows you to retrieve waypoint information by manually entering the waypoint’s name with the rocker keypad.
Waypoints can be deleted individually, by common symbol or all at once. Select the desired ‘Delete’ option and press ENTER.

To rename a waypoint, enter the new name directly over the old and press ENTER.

To Spell ‘n Find a waypoint:
1. Select the Spell ‘n Find option and use the rocker keypad to enter the first few characters of the waypoint name.
2. Press ENTER to view waypoints starting with characters entered.

Delete Waypoint— allows you to delete the waypoint which is highlighted on the Waypoint List.

Delete by Symbol— allows you to select a waypoint symbol and all waypoints with this corresponding symbol will be deleted from memory.

Delete All— deletes all waypoints currently stored in memory.

To delete a waypoint (or waypoints):
1. Select the desired delete option from the list above and press ENTER. The GPS 12 MAP will delete all waypoints not used in a route, then prompt you to continue before deleting any route waypoints.
2. If ‘Delete by Symbol’ is selected, select the desired symbol and press ENTER.

Editing Waypoints

Once you have created and stored a waypoint, it may be modified, reviewed, renamed or deleted at any time through the Waypoint Edit Page. The Waypoint Edit Page for any stored waypoint can be retrieved by highlighting the desired waypoint on the map display, or selecting it from any waypoint list, and pressing the ENTER key.

To access the Waypoint Edit Page:
1. Use the rocker keypad to highlight the desired waypoint on the map display or on any waypoint list.
2. Press ENTER to display the Waypoint Edit Page for the selected waypoint.
From the Waypoint Edit Page, highlight the appropriate field to rename a waypoint, change its symbol, edit the comment or edit the position.

**To rename the waypoint:**
1. Highlight the waypoint name field and press ENTER.
2. Use the rocker keypad to enter the new waypoint name and press ENTER.
3. If finished, highlight 'Done' and press ENTER.

**To change the waypoint's symbol:**
1. Highlight the waypoint symbol field and press ENTER.
2. Use the rocker keypad to select the desired symbol and press ENTER. The selected symbol will be used to denote the waypoint position on the map display.
3. If finished, highlight 'Done' and press ENTER.

When a waypoint is created, the time and date of creation is automatically added as a waypoint comment. You can edit this information or create an entirely new comment, as needed.

**To edit the waypoint comment:**
1. Highlight the waypoint comment field and press ENTER.
2. Use the rocker keypad to enter the desired comment and press ENTER.
3. If finished, highlight 'Done' and press ENTER.

**To edit the waypoint position:**
1. Highlight the waypoint coordinates field to change the position coordinates, or highlight the reference waypoint name, bearing or distance fields to change the reference waypoint information. Press ENTER to begin editing.
2. Use the rocker keypad to enter the new information. Press ENTER to accept the new information.
3. When finished, highlight 'Done' and press ENTER.
The Waypoint Edit Page also features an options page that allows you to delete the waypoint, view the map area around the waypoint position, define how the waypoint will appear on the map display or average the waypoint position to improve accuracy.

**To display the Waypoint Edit Options, press MENU (with the Waypoint Edit Page displayed).**

The following options are available:

- **Show Map**— allows you to view the map area surrounding the selected waypoint’s position. While viewing the map display, you can also use the IN and OUT zoom keys to see additional detail.

- **Display Options**— lets you designate how the selected waypoint will appear on the map display. Options are provided to show Symbol & Name, Symbol & Comment (Cmnt), or Symbol Only.

To change the display options for a waypoint:

1. Highlight ‘Display Options’ and press ENTER.
2. Highlight the desired option and press ENTER.

- **Average Position**— allows you to average position samples over time to update the waypoint’s position with a more accurate position reading. (See page 29 for more information on averaging.)

- **Delete Waypoint**— allows you to remove the selected waypoint from memory.

To delete a waypoint:

1. Highlight ‘Delete Waypoint’ and press ENTER. A confirmation screen is displayed.
2. ENTER to delete (or QUIT to cancel).
Another waypoint feature of the GPS 12 MAP is the nearest locations pages, which show up to nine nearest waypoints and 50 nearest cities—within 200 miles of your present position—along with 50 exits on the nearest (interstate) highway. The nearest locations pages are organized by a series of "file tabs" (denoting categories for Waypoints, Cities and Exits) and display the bearing (BRG) and distance (DST) to each nearby location for the selected tab (category). The lists are continuously updated as you’re moving and provide quick access to the closest points of safety in an emergency.

To view the nearest locations pages:

1. Press the MENU key twice to display the Main Menu.
2. Highlight ‘Nearest’ and press ENTER.
3. Highlight the appropriate tab (Waypoints, Cities or Exits) for the desired nearest list.
4. Scroll through the list using the UP/DOWN portion of the rocker keypad.

To view additional information for a nearby location:

1. Scroll through the selected nearest list (as described above) and highlight the desired location (Waypoint, City or Exit).
2. Press ENTER to display an info page for the selected location.
3. For waypoints, the information is displayed on the Waypoint Edit Page. You can edit the waypoint’s location, name, symbol, etc. from this page, as outlined on pages 47.
4. For cities, the information includes state, country, size or reference, and position. You can show the map area for the city, save it as a waypoint or switch between size and reference information as described on pages 65-66.
5. For exits, all the exit services pages and related options menus (described on pages 33-34) are available.
To GOTO a nearby location:

1. Highlight the desired location on the selected nearest list. Press GOTO to display the GOTO Page with the desired location selected.
2. Press ENTER to confirm the selected waypoint and begin navigating.

Nearest Location Options

The nearest locations pages also feature an options page—for the ‘Exits’ list—that allows you to define the category of exits you want to appear on the Nearest Exits List or restore the factory default settings after you’ve made any changes.

To display the nearest location options for Exits:

1. From the nearest locations pages, highlight the ‘Exits’ tab and press MENU.
2. Highlight the desired option and press ENTER.

The following options are available:

- **Exits Setup**— allows you to define the exit categories you wish to display on the Nearest Exits List. The categories include exits with or without services, rest areas, service areas, toll booths and welcome centers.

  1. Highlight ‘Exits Setup’ and press ENTER.
  2. Highlight the field adjacent to the desired category and press ENTER to enable/disable the category.

- **Restore Defaults**— resets all exit settings to the factory defaults. In this instance, it enables all exit categories.

  **NOTE:** An equivalent Setup Option is available for ‘Cities’.
The GPS 12 MAP can navigate to a destination using any of four different methods:

**GOTO**— lets you select a waypoint as your destination and quickly plot a direct course from present position to that waypoint.

**MOB (man overboard)**— captures your present position, saves it as a waypoint and sets a course back to the position for quick response in an emergency.

**TracBack**— allows you to retrace your path using the track log automatically stored in the receiver’s memory. This eliminates the need to store waypoints along the way. (See page 54 for more information about TracBack.)

**Routes**— allows you to manually create a sequence of intermediate waypoints which lead you to your final destination. The GPS 12 MAP will store up to 20 reversible routes, with up to 30 waypoints in each route.

### GOTO Navigation

The easiest way to select your destination is by using the GOTO key. The GOTO key can be used by itself, after highlighting a waypoint name on a list, or after designating a position on the map display.

#### To GOTO a waypoint:

1. Press GOTO. The GOTO Page shows a series of file tabs for ‘Recent’ waypoints, ‘All’ waypoints, ‘Nearest’ waypoints or ‘Spell n Find’.

2. To GOTO a recently used waypoint or a nearby waypoint, select the ‘Recent’ tab or the ‘Nearest’ tab, highlight the desired waypoint on the list and press ENTER.

3. To GOTO any waypoint stored in memory, select the ‘All’ tab, highlight the desired waypoint and press ENTER.

4. To enter the name of the destination waypoint, highlight the waypoint name field and press ENTER. (The ‘Spell n Find’ tab is automatically selected.) Use the rocker keypad to enter the name of the desired waypoint—UP/DOWN to change each character and RIGHT to move to the next character. Press ENTER to confirm the selection.
To designate a GOTO waypoint from a list of waypoints:

1. Highlight the desired waypoint on the list and press GOTO. A confirmation page shows the selected destination waypoint.
2. Press ENTER to confirm the selected waypoint and begin navigating.

To GOTO an existing waypoint, city or highway exit on the map display:

1. Use the rocker keypad to place the arrow on the desired target location. If a city or exit is selected, a waypoint will be created at that location using the city or exit name.
2. Press GOTO, followed by ENTER, to begin navigating.

To GOTO any position on the map display:

1. Use the rocker keypad to place the arrow on any position you wish to navigate to.
2. Press GOTO to create a waypoint, called 'MAP', at the arrow position. Each time you perform this step it will overwrite any previously created 'MAP' waypoint.
3. Press ENTER to begin navigating.

GOTO Options

GOTO Options are also provided to initiate a TracBack route or cancel the current GOTO destination.

To display the GOTO Options, press MENU (immediately after pressing GOTO).

The following options are available:

**TracBack**— allows you to retrace your path using the track log automatically stored in the receiver’s memory. This eliminates the need to store waypoints along the way. (See page 54 for more information about TracBack.)
**Cancel GOTO**—cancels the current GOTO destination and resumes navigation of any previously selected route. If no route is currently in use; bearing, distance, etc. will remain blank until a destination waypoint is defined.

**To cancel the current GOTO destination,** highlight ‘Cancel GOTO’ and press ENTER.

**MOB (man overboard)**

The GPS 12 MAP’s MOB function lets you simultaneously mark and set a course to a position for quick response in an emergency. Once an MOB has been activated, an MOB symbol will appear on the map display and the navigation screens will guide you back to the ‘MOB’ waypoint.

**To activate the MOB function:**

1. Press and hold GOTO to capture the MOB position.
2. Press ENTER to begin navigating back to the ‘MOB’ waypoint.
3. To cancel the MOB function, select ‘Cancel GOTO’ from the GOTO Options and press ENTER.

**NOTE:** Each time an MOB is activated, any previous ‘MOB’ position stored in memory will be overwritten and permanently lost. If you wish to save an ‘MOB’ waypoint for future use, you should give the waypoint a new name using the steps outlined on page 47.
Clear any old data from the active log before you depart. This defines the starting point for a TracBack Route.

A TracBack route can also be created from the GOTO Options by pressing GOTO, followed by MENU and selecting 'TracBack'.

The TracBack navigation feature allows you to retrace your path using the track log automatically stored in the receiver's memory. This eliminates the need to manually store waypoints along the way. A track log is an electronic breadcrumb trail, showing the path you have travelled. Your GPS 12 MAP can be set to automatically record track log points any time the receiver is on and locked onto satellites (see page 70).

TracBack routes are created by reducing your track log into a route of up to 30 waypoints and activating the new route in reverse order along those waypoints. Once activated, a TracBack route will lead you back to the oldest track log point stored in memory, so it's a good idea to clear the active track log at the beginning of your current trip (e.g., at the dock or trailhead), before you get started.

To clear the active track log and define a starting point for a TracBack:

1. Press MENU twice to display the Main Menu.
2. Highlight 'Track Logs' and press ENTER.
3. With the 'Active Log' highlighted press MENU to display the options list.
4. Highlight 'Clear Active Log' and press ENTER.
5. Press ENTER to delete the track log data. (Or press QUIT to cancel.)

To create and activate a TracBack route:

1. Enable track log recording and leave the GPS 12 MAP on to automatically record track log positions while under way. Refer to page 70 for more information on track log settings.
2. Press MENU twice to display the Main Menu.
3. Highlight 'Track Logs' and press ENTER.
4. Highlight the desired track log ('Active Log' or 'Saved Logs') and press MENU to display the options list.
5. Highlight 'TracBack' and press ENTER to create/activate the TracBack route. (A message box will appear while the GPS 12 MAP analyzes the data and creates the route.)
Once a TracBack has been activated, the GPS 12 MAP will take the track log currently stored in memory and divide it into route segments, called ‘legs’. Up to 30 track log waypoints (labeled ‘T###’, e.g. ‘T001’) will be created to mark the most significant features of the track log in order to duplicate your path as closely as possible. To gain the most benefit from the TracBack feature, keep the following tips in mind:

- Always clear the track log at the point you want to return to (boat ramp, dock, trailhead, etc.)
- The ‘Record Mode’ on the Track Logs Page must be set to ‘Wrap’ or ‘Fill’.
- There must be at least two track log points stored in memory to create a TracBack route.
- If there is not enough available memory to add more waypoints and create a TracBack route, you will be alerted with a ‘waypoint memory full’ message. The receiver will use the available waypoints to create a route with an emphasis on the track log data closest to the destination. Also, existing TracBack waypoints (‘T###’) that are not contained in routes will be erased to free more memory. The GPS 12 MAP will create new waypoints using the first available three-digit number.
- If the Track Logs Page ‘Interval’ field is set to ‘Time’, the route may not follow your exact path. (Keep the ‘Interval’ field set to ‘Resolution’ for best results.)
- If the receiver is turned off or satellite coverage is lost during your trip, TracBack will draw a straight line between any point where coverage was lost and where it resumed.
- If there are frequent changes in direction and distance in your track log, 30 waypoints may not accurately depict your exact path. The receiver will then assign the 30 waypoints to the most significant points of your track log, and simplify segments with fewer changes in direction.
Route navigation allows you to manually create a sequence of intermediate waypoints which lead you to your final destination. The GPS 12 MAP will store up to 20 reversible routes, with up to 30 waypoints in each route. Routes can be created and modified by text entry (using the rocker keypad to enter waypoint names) or directly from the map display. Using the map display allows you to see each route graphically on-screen as you create, review, modify or navigate the route. All of the GPS 12 MAP’s route functions are accessed through the Main Menu.

**To create a new route by entering the name of each waypoint:**

1. Press MENU twice to display the Main Menu.
2. Highlight ‘Routes’ and press ENTER. The Route List is displayed, showing all routes stored in memory.
3. Press MENU to display the Route Options.
4. Highlight ‘New Route’ and press ENTER. The GPS 12 MAP creates a route called ‘EMPTY-1’. (The name changes as you add waypoints to the route, so make note of the route name for future reference.)
5. Highlight the first waypoint name field and press ENTER to begin entering the name of an existing waypoint in memory.
6. Use the rocker keypad to enter the name of the route waypoint.
7. Press ENTER to accept the selected route waypoint.
8. Highlight the next waypoint name field, press ENTER and repeat steps 6 & 7 until all the waypoints have been added to the route.
To create a route from the map display:

1. Press MENU twice to display the Main Menu.
2. Highlight ‘Routes’ and press ENTER. The Route List is displayed, showing all routes stored in memory.
3. Press MENU to display the Route Options.
4. Highlight ‘New Route’ and press ENTER. The GPS 12 MAP creates a route called ‘EMPTY-1’. (The name changes as you add waypoints to the route, so make note of the route name for future reference.)
5. Press MENU to display the New Route Options and highlight ‘Show Map’.
6. Press ENTER and use the rocker keypad to place the arrow over the first route waypoint. (Use the IN and OUT zoom keys to aid in locating the desired waypoint.)
7. Press ENTER to accept the selected route waypoint.
8. Highlight the next waypoint on the map display and press ENTER to add the waypoint to the route. Repeat this step until all route waypoints have been added to the route. Press PAGE or QUIT to exit the page.
9. You can also create route waypoints during this process. If no waypoint exists at the arrow location, the GPS 12 MAP will automatically create one—using a three digit number as the waypoint’s name. (You can rename the waypoint following the steps on page 47.)
10. If you wish to include a city location in the route, place the arrow over the city and press ENTER. A confirmation page will appear with the name of the city as a new waypoint (sometimes abbreviated, depending on the length of the original name). To add to the route, select ‘Use’ and press ENTER.

As you add each new waypoint to the route, the data window at the top of the map display will show the name of the route you are creating, which includes the first and last waypoints in the route. A solid route line will appear on the map to indicate each leg, and a dotted line will appear to indicate the distance and bearing from the last route waypoint to the cursor position.

You can add city (or highway exit) locations to a route by placing the editing arrow on a city (or highway exit) and pressing ENTER.
The GPS 12 MAP’s Route List displays all the routes currently stored in memory, along with a descriptive name for each route. Once a route has been created, it can be activated and used for navigation from the Route List. A route may be followed in the same sequence as it was originally created, or you can invert the route and navigate from the end waypoint back to the beginning waypoint.

**To activate a route:**

1. Press MENU twice to display the Main Menu.
2. Highlight ‘Routes’ and press ENTER. The Route List is displayed, showing all routes stored in memory.
3. Highlight the desired route and press MENU to display the Route Options.
4. Highlight ‘Activate’ and press ENTER to navigate the route in sequence.

**To deactivate the route and stop using it for navigation:**

1. Press PAGE repeatedly to display the Active Route Page. (See page 62.)
2. Press MENU to display the Active Route Options.
3. Highlight ‘Deactivate’ and press ENTER to stop navigating the currently selected route.

The Route List also allows you to enter your own 13-character name for any listed route. By default the name includes the first and last waypoints in the route.

**To enter a custom route name:**

1. Press MENU twice to display the Main Menu.
2. Highlight ‘Routes’ and press ENTER. The Route List is displayed, showing all routes stored in memory.
3. Highlight the desired route and press ENTER to display the Route Plan Page.
4. Highlight the name field and press ENTER to begin editing.
5. Use the rocker keypad to enter the desired name and press ENTER when finished.
Route Editing

Once a route is added to memory you can review and/or edit the route from the Route Plan Page. The Route Plan Page shows the sequence of waypoints for the selected route and provides additional options to depict the route layout on the map display, insert waypoints, remove waypoints or perform trip/fuel planning functions.

To edit a route:

1. From the Route List, highlight the route you wish to edit and press ENTER. The Route Plan Page appears for the selected route.

2. To change a route waypoint, highlight the waypoint you wish to change and press ENTER. Use the rocker keypad to enter the new waypoint and press ENTER.

3. To review the information for a route waypoint, highlight the desired waypoint and press MENU. A pop-up menu appears with additional options. Highlight ‘Review Wpt’ and press ENTER to display information for the selected waypoint.

4. To insert a waypoint in the route, highlight the waypoint that will immediately follow the new route waypoint and press MENU. A pop-up menu appears with additional options. Highlight ‘Insert Wpt’ and press ENTER to display a blank line for the new waypoint. Enter the name of the new waypoint, using the rocker keypad, and press ENTER.

5. To delete a waypoint from the route, highlight the waypoint you wish to delete and press MENU. A pop-up menu appears with additional options. Highlight ‘Remove Wpt’ and press ENTER.

6. To edit the route from the map display, press MENU from the Route Plan Page. Highlight ‘Show Map’ and press ENTER. Use the rocker keypad to place the cursor on the desired waypoint and press MENU. A pop-up menu appears. Select the desired option and press ENTER. If ‘Move’ is selected, move the cursor to the desired location and press ENTER to accept the change.
Route Planning

The Route Plan Page also displays trip planning information for each leg or the entire route. Available information includes desired course, time to waypoint, distance to waypoint, required fuel and sunrise/sunset times at the waypoint location.

To use the trip planning features:

1. To select the desired planning figure, highlight the desired route from the Route List and press ENTER to display the Route Plan Page. One of ten available planning figures appears to the right of each route waypoint. Use the LEFT/RIGHT keys on the rocker keypad to select the desired item.

2. To enter planning information, Press MENU and select 'Setup Plan' from the options list. Enter the figures for speed, fuel flow, departure time and departure date. Press QUIT to return to the Route Plan Page.

NOTE: Fuel flow rates on your GPS 12 MAP are measured in “units per hour”. System setting changes for units of measure (statute, nautical or metric) do not affect the fuel flow measure. You should enter fuel flow rates based upon available information for your vehicle (operator’s manual, performance specifications, etc.) and make note of the desired units of measure (gallons, liters, etc.)

When a route is highlighted on the Route List, additional functions are available from the Route Options.

To display the Route Options, press MENU (with the Route List displayed).
The following options are available:

**New Route** — allows you to create a new route, as described on page 56.

**Activate** — allows you to navigate the route in the same sequence it was originally created, as described on page 58.

**Copy** — allows you to copy the selected route to a new route. The copy function can be used to save a TracBack route for future use. The copy function is also useful for duplicating an existing route before making changes.

**Delete Route** — allows you to remove the selected route from memory. The waypoints contained in the route will still appear in memory, but not as part of the route.

**Delete All** — allows you to remove all routes from memory. The waypoints contained in all stored routes will remain in memory, but not as part of any route.

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**To copy a route:**

1. Highlight the desired route on the Route List and press MENU.
2. Highlight ‘Copy’ and press ENTER.
3. The Route Plan Page will appear for the duplicate route and the name for the new route will be identical to the original, but followed by a number (e.g. ‘HOME-CAMP 1’).

**To delete a route from memory:**

1. Highlight the desired route on the Route List and press MENU.
3. Press ENTER to delete the route (or QUIT to cancel).

**To delete all routes from memory:**

1. Highlight ‘Delete All’ and press ENTER. A confirmation page will appear.
2. Press ENTER to delete all routes (or QUIT to cancel).
Route Options / Active Route

The Active Route Page

The last page appearing in the main sequence (using the PAGE or QUIT keys) is the Active Route Page. Whenever you have activated a route, GOTO, MOB or TracBack, the Active Route Page will show each waypoint (by name) of the active route, along with the desired course, distance to waypoint, time to each waypoint, fuel requirements or sunrise/sunset times at each route waypoint. As you navigate the route, the information on the Active Route Page will automatically update to indicate the destination waypoint and any remaining interim waypoints—with the next point along the route denoted by an arrow on the left-hand side of the screen.

From the Active Route Page you can change the name of the active route (see page 58), review information on a route waypoint (see page 59) or bypass route waypoints and GOTO any waypoint in the route (see page 52). The user-selectable data field on the right side of the page also keeps you informed of current conditions. There are ten different data items available.

To change the Active Route Page data, press the LEFT/RIGHT keys on the rocker keypad.
Many features of the GPS 12 MAP are menu driven. Each of the main pages has an options menu, allowing you to custom tailor the corresponding page to your preferences and/or select special features which specifically relate to that page.

**To display the Active Route Page Options, press MENU (with the Active Route Page displayed).**

The following options are available:

- **Show Map**— allows you to view the area around the active route. When selected, ‘Show Map’ will show the map display centered on the first waypoint in the active route.

- **Setup Plan**— displays a trip planning screen, allowing you to plan and review distance, fuel, time en route and sunrise/sunset information for the selected route.

**To use the trip planning features:**

1. Highlight ‘Setup Plan’ and press ENTER. The trip planning screen is displayed, showing speed, fuel flow, departure time and departure date information.

2. Enter an hourly fuel flow (if desired) in the fuel field, using the same steps above. Fuel flow rate units (gallons, liters, etc.) are not specified on the GPS 12 MAP. Enter these figures based upon available information for your vehicle and make note of the desired units.

3. Press QUIT to return to the Route Plan Page, then use the LEFT/RIGHT keys on the rocker keypad to review the planning information.

- **Re-evaluate**— reactivates the current route and selects the route leg closest to your current position as the active leg. The active leg defines the current ‘from’ and ‘to’ waypoints.
Deactivate—cancels navigation of the route you are currently using. See page 58.

Invert—reactivates the current route in reverse order and navigates from the end waypoint back to the beginning waypoint. See page 59.

Insert Wpt—allows you to insert an additional waypoint into the route, directly in front of the currently highlighted waypoint in the route. If no route waypoint is highlighted, this option is not available. See page 59 for route editing info.

Remove Wpt—removes the currently highlighted waypoint from the route. If no waypoint is highlighted, this option is not available. See page 59 for route editing information.

Review Wpt—allows you to view information for the currently highlighted waypoint in the route. If no route waypoint is highlighted, this option is not available. See page 47 for waypoint review information.

Delete Route—allows you to remove the current route from memory. The waypoints contained in the route will still appear in memory, but not as part of the route. See page 61.
The GPS 12 MAP's Main Menu provides access to the waypoint, route, track log, timer and setup features of the receiver. The Main Menu can be accessed at any time using the MENU key.

**To display the Main Menu, press the MENU key twice.**

The 7 menu options are divided into categories by function: waypoints/cities/nearest locations, routes/track logs, trip computer, and system setups.

**To select an option from the Main Menu, highlight the desired item and press ENTER.**

The following menu options are available (continued on the next five pages):

**Waypoints**— allows you to create, edit or delete waypoints. See pages 43-48.

**Cities**— allows you to search the built-in database for a particular city or town. The City Spell 'n Find Page will display the location, size/reference, bearing and distance to the selected city. (Categories for small towns and small/medium/large cities are provided, based on the population levels described on page 66.)

**City Spell 'n Find**

**To select a city and display it on the City Spell 'n Find Page:**

1. Highlight 'Cities' from the Main Menu and press ENTER.

2. The first character of the city name field should already be highlighted. Enter the name of the desired city using the ROCKER KEYPAD—UP/DOWN to change the highlighted character, and RIGHT to move to the next character. As you spell the name of the desired city, the GPS 12 MAP will display the first entry in the built-in database which corresponds to the characters you have entered.
Main Menu:
City Options

City Spell 'n Find

ATLANTA
State/Country
Georgia
USA
Size
Large City
Position
N 33°45.824'
H084°25.302'

The City Spell 'n Find Page lets you retrieve information for any city in the built-in database.

If duplicate entries exist for the desired city, continue scrolling through the database entries using the UP/DOWN keys on the ROCKER KEYPAD. (When the same city name exists in several states/countries, pay particular attention to the 'State/Country' field directly below the city name field.)

3. Once the desired city is displayed, press ENTER to accept the selection.

City Spell 'n Find Options

To view the City Spell 'n Find Options, press MENU (with the City Spell ‘n Find Page displayed).

The following options are available:

Show Map - allows you to view the map area surrounding the selected city's position. While viewing the map display, you can also use the IN and OUT zoom keys to see additional detail.

To view the map area around the city location:

1. Select 'Show Map' and press ENTER.

Save As Waypt - creates a waypoint at the city location and saves it in memory. If the city name is longer than six characters, it will be abbreviated when creating the waypoint.

To save an exit location as a waypoint:

1. Select 'Save As Waypt' and press ENTER.
2. With 'Done' highlighted, press ENTER to save the new waypoint.

Show Reference / Show City Size - allows you to toggle between a reference waypoint field or size information. The reference waypoint field allows you to determine bearing and distance from any waypoint to the selected city. The size information block describes the size of the selected city as follows: Large cities are those with approximate populations greater
than 200,000. Medium cities are greater than 50,000 and small cities are greater than 5,000. Small towns include those with approximate populations under 5,000 or towns of unknown size.

**NOTE:** When the 'Reference' field is left blank or the size information field is displayed, the 'Bearing' and 'Distance' information provided is from your current position.

**To select between size information and a reference waypoint field:**

1. Select 'Show City Size' or 'Show Reference' (as appropriate) and press ENTER. (When one of the options is selected, the other option will appear on the City Spell 'n Find Options menu.)

2. If 'Show Reference' is selected, the City Spell 'n Find Page will reappear.

**To enter a reference waypoint and display the bearing and distance from the waypoint to the selected city:**

1. Select the 'Show Reference' option, as described above.

2. With the cursor highlighting the reference waypoint field, press ENTER to begin entering the reference waypoint name.

3. Use the ROCKER KEYPAD to enter the name of the reference waypoint and press ENTER when finished. The bearing and distance from the reference waypoint to the city location will appear at the bottom of the screen.

**Nearest**— displays up to nine nearest waypoints and 50 nearest cities within 200 miles of your present position, along with 50 exits on the nearest interstate highway. See page 49.

**Routes**— allows you to create, edit, activate or delete routes. See pages 56-59.
Track Log—lets you specify whether or not to record a track log (an electronic 'breadcrumb trail' recording of your path), define how it is recorded or save track log data for future use. The Track Logs Page also provides an indicator of the memory used for the active track log and options to clear the track memory or start a TracBack route. See pages 54-55 for TracBack information.

The Track Logs Page is divided into two main sections: one for the active log (the log currently being recorded) and available memory, and the second section showing any saved track logs and the total number saved. The active log stores up to 1900 track log positions, based upon the criteria specified in the Track Log Options. Up to 10 additional track logs may be saved in memory, with up to 250 track log positions in each saved log.

**Track Log Settings**

To view the Track Log Options, highlight 'Active Log' or any of the 'Saved Logs' (on the Track Logs Page) and press MENU.

The following options are available:

- **TracBack** - converts the track log data in memory into an inverted route (of up to 30 waypoints) and begins navigation along the route. See pages 54-55.

- **Save Active Log** - extracts up to 250 of the most significant points along the active log, saves this information as a 'saved log', and clears the active log. Up to 10 saved logs may be stored in memory, along with a 13-character name. The default name is the date the log was saved, but you can specify any name you wish. You can prevent the active log from being cleared by pressing QUIT when prompted.
To rename a saved log:
1. Highlight the saved log you wish to rename and press ENTER. An information box appears, showing the name of the saved log, the number of points in the track log and the total distance covered.
2. Highlight the track log name field and press ENTER.
3. Use the rocker keypad to enter the new name for the saved log. Press ENTER when finished.

**Clear Active Log / Delete Saved Log** - clears the selected track log, active or saved, from memory. Highlight the ‘Active Log’ to display the ‘Clear Active Log’ option, or highlight any of the ‘Saved Logs’ to display the ‘Delete Saved Log’ option. You should select the ‘Clear Active Log’ option at the beginning of any trip where you’ll want to convert the track log data into a TracBack route. See pages 54-55.

To delete a track log:
1. Highlight the track log you wish to delete (active or saved) on the Track Logs Page, and press MENU to display the Track Log Options.
2. Highlight ‘Clear Active Log’ or ‘Delete Saved Log’ and press ENTER.
3. Press ENTER again to confirm (or press QUIT to cancel).

**Delete All** - allows you to clear all track logs, active and saved, from memory.

To delete all track logs from memory:
1. Select ‘Delete All’ from the Track Log Options and press ENTER.
2. Press ENTER again to confirm (or QUIT to cancel).
Setup Logging - provides a setup screen to define how track log data will be recorded. The Setup Logging Page provides options for 'Record Mode', 'Interval' and 'Interval Value'. Record Mode lets you select one of three track recording options:

'Off' – No track log will be recorded.

**NOTE:** Selecting 'Off' will prevent you from using the TracBack feature.

'Fill' – A track log will be recorded until the track memory is full.

'Wrap' (default) – A track log will be continuously recorded, wrapping through available memory; replacing the oldest track data with new data.

Interval defines the frequency with which the track plot is recorded. Three interval settings are available:

'Resolution' (default) – Records track log based upon a user-defined variance from your course over ground. The resolution option is recommended for the most efficient use of memory and TracBack performance. The distance value (entered in the 'Interval Value' field) is the maximum left/right deviation allowed from the last defined ground track before recording a new point.

'Time' – Records track log based on a user-defined time interval.

'Distance' – Records track log based on a user-defined distance between points.

Interval Value defines the distance or time interval used to record the track log.

**Trip Computer**— provides readouts for average speed, maximum speed, odometer, trip odometer and trip timer. These readouts can be reset from the Trip Computer Options.
To reset a trip computer readout(s):

1. Press MENU (with the Trip Computer Page displayed). An options list is displayed.
2. To reset all trip computer readouts, highlight ‘Reset All’ and press ENTER.
3. To reset a single readout item, highlight the desired option and press ENTER.
4. To log trip time only while moving, highlight ‘Use Time Moving’ and press ENTER. If this option is selected, ‘Use Total Time’ will appear instead. This latter option logs trip time any time the GPS 12 MAP is on and has a position fix.

NOTE: The ‘Reset Trip’ option resets trip odometer, trip timer and average speed readouts.

Setup—provides a group of pages to perform various system setup functions, including selection of position format, units of measure, setting various alarms, and backlighting. Each available page is denoted by a ‘file tab’ that identifies the function of that page.

To select a Setup option, highlight the file tab for the desired function. The information is automatically displayed when the file tab is highlighted.

The file tab headings and setup functions for these pages are:

**Simulator**—Enable/Disable; Settings for simulated Track, Speed and Altitude

**System**—Beeper Setting, Backlight timeout, Battery type, and Power Saver Mode

**Units**—Units of measure settings for – Distance & Speed, Heading and Altitude

**Timers**—Count up/down User Timer, Battery

To display the desired information, highlight the appropriate file tab (using the LEFT/RIGHT keys on the rocker keypad).

Once the desired tab is selected, use the UP/DOWN keys on the rocker keypad to select the desired item on the page.
The built-in simulator feature allows you to configure and control the behavior of the simulator. This includes enabling or disabling the simulator, setting the speed, and controlling the track heading.

### Simulator Settings

1. **Mode**
   - Allows you to turn the built-in simulator on or off.
   - **To enable/disable the built-in simulator:**
     1. Highlight the ‘Mode’ field and press ENTER.
     2. Select ‘Simulator Off’ or ‘Simulator On’ (as desired) and press ENTER.

2. **Speed**
   - Lets you select a simulated speed when the simulator is enabled.

3. **Track Control**
   - Allows the built-in simulator to automatically align track heading to the desired course (when using a GOTO or route), or allows you to manually adjust the track heading, as desired.

4. **Track**
   - Allows you to manually enter a track heading. This setting is only available when Track Control is set to ‘User Track’.

5. **Altitude**
   - Allows you to specify a user-defined altitude for your simulated position.

### To select a simulator setting:

1. For track control, highlight the ‘Track Control’ field and press ENTER. Select ‘Auto Track’ or ‘User Track’ and press ENTER.
System Settings

Beeper lets you turn on or off an audible beep when any key is pressed or when an on-screen message appears to alert you to important information.

Backlight lets you keep the screen backlighting on continuously (‘always on’) when selected, or enable the automatic shutoff to preserve battery life. Automatic shutoff times from 15 seconds to 4 minutes (since last key press) are available.

To set the backlight timeout:
1. Highlight the ‘Backlight’ field and press ENTER.
2. To keep backlighting on continuously, select ‘Always On’ and press ENTER, OR
3. To set a timeout duration, select the desired time period and press ENTER.

Battery is used to designate the type of batteries currently being used to power your GPS 12 MAP: Alkaline, Lithium or NiCad. This setting ensures accurate readings from the battery gauge on the Satellite Status Page (see page 25).

Power Saver is suitable for most applications and offers position updates which adapt to your needs while extending battery life. The GPS 12 MAP will operate up to 36 hours when using Power Saver mode.

To select power saver mode:
1. Highlight the ‘Power Saver’ field and press ENTER.
2. Use the UP/DOWN keys on the ROCKER KEYPAD to select ‘ON’ (or ‘OFF’) and press ENTER.
Setup Menu: Units

The ‘User Mag’ option allows you to define the magnetic variation for your area. ‘Auto Mag Var’ is the preferred setting in most cases.

**Units Settings**

**Distance & Speed** lets you select the desired units of measure for distance and speed readouts in ‘Nautical’, ‘Statute’ or ‘Metric’ terms.

**Heading** lets you select the reference used in calculating heading information. You can select from ‘Auto Mag Var’, ‘True’, ‘Grid’ and ‘User Mag Var’. ‘Auto Mag Var’ provides magnetic north heading references which are automatically determined from your current position. ‘True’ provides headings based upon a true north reference. ‘Grid’ provides headings based on a grid north reference (and is used in conjunction with the grid position formats described on page 78). ‘User Mag Var’ allows you to specify the magnetic variation at your current position and provides magnetic north heading references based upon the variation you enter.

**Altitude/Elevation** lets you select altitude readouts in ‘Feet’ or ‘Meters’.

**To select a units setting:**

1. Highlight the desired field and press ENTER to display the available options.
2. Select the desired option and press ENTER.
3. If ‘User Mag Var’ is selected in the ‘Heading’ field, highlight the heading reference field (immediately to the right) and press ENTER. Enter the magnetic variation at your current position using the rocker keypad and press ENTER.

**WARNING:** If ‘User Mag Var’ is selected, you must periodically update the magnetic variation as your position changes. Using this setting, the GPS 12 MAP will not automatically calculate and update the magnetic variation at your present position. Failure to update this setting may result in substantial differences between the information displayed on your GPS 12 MAP and external references, such as a magnetic compass.
**Timers Settings**

**User Timer** lets you select a count up or count down timer. For a count down timer you may also specify the count down duration.

**To select a user timer setting:**

1. For a count down timer, highlight the ‘User Timer’ field in the right-hand column, press ENTER and enter the count duration using the rocker keypad. Press ENTER to accept, then—with the left-hand column highlighted—press ENTER to view the User Timer options. Select ‘Down’ and press ENTER.

2. For a count up timer, highlight the ‘User Timer’ field in the left-hand column, press ENTER and select ‘Up’. Press ENTER to confirm.

3. To reset the timer or turn the timer off, highlight the ‘User Timer’ field in the left-hand column, press ENTER and select ‘Reset’ or ‘Off’ (as appropriate). Press ENTER to confirm.

**Battery Timer** provides a running count of how long the GPS 12 MAP has been in operation with the current batteries. The timer automatically stops when using an external power source. The timer will automatically reset when depleted batteries are replaced, but can also be manually reset.

**To select a battery timer setting:**

1. Highlight the ‘Battery Timer’ field in the left-hand column and press ENTER.

2. Select ‘Off’, ‘On’ or ‘Reset’ (as appropriate) and press ENTER.

**Since Midnight** provides a running count of how long the GPS 12 MAP has been in operation since midnight of the current day.

**Since Factory Reset** provides a running count of total GPS 12 MAP operating time since the receiver was shipped from the factory.
Setup Menu: Time

Enter an offset amount to adjust the time display to your local area. In the United States, all offset amounts will be ‘Behind UTC’.

**Time Settings**

**Time Format** allows current time to be displayed using a 12- or 24-hour clock. This field is also used to select between local and UTC time readouts.

**To select a time format:**

1. Highlight the ‘Time Format’ field and press ENTER to display the available options.
2. Select ‘Local 24hr’ or ‘Local 12hr’ to display local time references. ‘Local 12hr’ will show current time using a traditional AM/PM format, OR
3. Select ‘UTC’ to display universal time references (also referred to as ‘Greenwich’ or ‘zulu’ time).

**Local Time Zone** is used to define the current local time. UTC date and time are calculated directly from the satellites’ signals and cannot be edited. If you prefer to use local time, you may designate an offset, either ‘Behind UTC’ or ‘Ahead of UTC’. The offset is the difference, in hours and minutes, between local time and UTC time.

**To enter the local time zone:**

1. Highlight the ‘Local Time Zone’ field and press ENTER.
2. Select the desired offset amount (in hours and minutes) using the rocker keypad and press ENTER.
3. Highlight the offset direction field (immediately to the right) and press ENTER.
4. Select ‘Behind UTC’ or ‘Ahead of UTC’ (as appropriate) and press ENTER.

**Time** displays the current time based on the settings made above and information provided by the satellites received.

**Date** displays the current date based on the settings made above and information provided by the satellites received.
Alarms Settings

Clock Alarm uses the internal clock to provide an 'Alarm Clock' message at the time you set.

To enable/disable the alarm clock:

1. Highlight the 'Clock Alarm' field and press ENTER.
2. Select 'On' or 'Off' (as desired) and press ENTER.
3. If enabling the alarm, highlight the time field (to the immediate right) and press ENTER. Enter the alarm time using the rocker keypad and press ENTER.

NOTE: The GPS 12 MAP must be turned on when the alarm time is reached. Otherwise, the message will not occur.

Arrival Alarm provides an alarm message once you're within a set distance from your destination waypoint. As you approach the destination waypoint, an 'Arrival at ____' message occurs when you are within the alarm distance you entered.

Off Course Alarm provides an alarm message ('Off Course Alarm') when you deviate off course beyond the specified limits.

To set the arrival and/or off course alarms:

1. Highlight the 'Arrival Alarm' or 'Off Course Alarm' field and press ENTER.
2. Select 'On' or 'Off' (as desired) and press ENTER.
3. If enabling the alarm, highlight the alarm distance field (to the immediate right) and press ENTER. Enter the alarm distance using the rocker keypad and press ENTER.
**Position Settings**

**Position Format** is used to change the coordinate system in which a given position reading is displayed. The default format is latitude and longitude in degrees and minutes (hddd°mm.mmm'). The following additional formats are available:

- hddd.ddddd° — latitude/longitude in decimal degrees only
- hddd°mm.ss.s” — latitude/longitude in degrees, minutes, seconds
- UTM/UPS — Universal Transverse Mercator / Universal Polar Stereographic grids
- British Grid
- Irish Grid
- Swiss Grid
- Maidenhead
- User UTM Grid
- German Grid
- Swedish Grid
- Taiwan Grid
- New Zealand

**Map Datum** allows you to select the datum reference used to determine where a given position is. The default setting is ‘WGS 84’. Although over 100 datums are available (as listed on page 88-90), you should only change the datum if you are using a map or chart that specifies a different datum. If no datum is specified, you may select each datum applicable to your region until you find the datum that provides the best positioning at a known point.

**WARNING**: Selecting the wrong map datum can result in substantial position errors. When in doubt, use the default WGS 84 datum for best overall performance.
To change the position format and/or map datum:

1. Highlight the 'Position Format' or 'Map Datum' field and press ENTER.
2. Select the desired setting (using the rocker keypad) and press ENTER.

**Interface Settings**

**Format** lets you control the input/output format used when connecting your GPS 12 MAP to external NMEA devices, a DGPS beacon receiver, a personal computer, etc.

Five format settings are available:

- **GARMIN** — the proprietary format used to exchange waypoint, route, track log data with a PC or with another GPS 12 MAP.
- **NMEA** — supports the input/output of standard NMEA 0183 version 2.0 data.
- **None** — provides no interfacing capabilities.
- **RTCM/NMEA** — allows Differential GPS (DGPS) input using a standard RTCM format and also provides NMEA 0183 version 2.0 output.
- **RTCM Text** — allows DGPS input using a standard RTCM format, without any output capabilities.
- **Text Out** — allows DGPS output using a standard RTCM format, without any input capabilities.

Over 100 different datums are provided to allow the GPS 12 MAP to correspond to various paper charts/maps. Use WGS 84 unless your chart specifies otherwise.

The ‘GARMIN’ option allows the GPS 12 MAP to exchange data with a PC or another GPS 12 MAP. Use this setting with the optional PC Software Kit.
Select the ‘RTCM/NMEA’ option to use the GPS 12 MAP along with a GARMIN Differential Beacon Receiver.

To select an input/output format:

1. Highlight the ‘Format’ field and press ENTER.
2. Select the desired setting and press ENTER.
3. If the ‘GARMIN’ format is selected, highlight the ‘Transfer Mode’ field and press ENTER. Select the desired setting and press ENTER. The ‘Transfer Mode’ field allows you to specify what information to request or send to a second GPS 12 MAP. The ‘Host’ setting lets you control all data transfer functions from the second GPS 12 MAP or from a PC.
4. If an ‘RTCM’ format is selected, additional fields are provided to control a GARMIN differential beacon receiver (e.g. GBR 21) directly from your GPS 12 MAP. You can enter the beacon frequency and bit rate on the GPS 12 MAP and the information will be used to tune the beacon receiver. For more information, refer to the owner’s manual for your GARMIN differential beacon receiver.
The GPS 12 MAP is constructed of high-quality materials and should not require user maintenance. If your unit ever needs repair, please take it to an authorized GARMIN service center. Never attempt any repairs yourself. To protect your GPS 12 MAP, keep it in a covered container or case when not in use, and never allow gasoline or other solvents to come into contact with the case. Clean the case and lens with a soft cloth and a household window cleaner.

**APPENDIX A**

**Specifications**

**PHYSICAL**
- **Case:** Waterproof to IPX7 standards
- **Size:** 5.3 x 14.7 x 3.1 cm
- **Weight:** Approx. 9.5 ounces (269g) w/ batteries
- **Temp. Range:** 5º to 158ºF (-15º to 70ºC)

**PERFORMANCE**
- **Receiver:** 12 parallel channel, differential-ready
- **Acquisition Time:**
  - Approx. 15 seconds (warm start)
  - Approx. 45 seconds (cold start)
  - Approx. 5 minutes (AutoLocate™)
- **Update Rate:** 1/second, continuous
- **Position Accuracy:**
  - 1-5 meters (3-17 ft.) with DGPS corrections*
  - 15 meters (49 ft.) RMS**
- **Velocity Accuracy:** 0.1 knot RMS steady state
- **Dynamics:** 6g

**POWER**
- **Input:** Four 1.5 volt AA batteries† or 10-32 VDC
- **Power Usage:** 1 watt
- **Battery Life:** Up to 36 hours (with 4 AA batteries) in Power Saver mode‡
- **Internal Backup:** Lithium battery

Specifications subject to change without notice.

* With optional DGPS input.
** Subject to accuracy degradation to 100m 2DRMS under the US DOD-imposed Selective Availability Program.
† The temperature rating for the GPS 12 MAP may exceed the usable range of some batteries. Alkaline batteries can rupture at high temperatures.
‡ Alkaline batteries lose a significant amount of their capacity as temperature decreases. If you’re using the GPS 12 MAP in below freezing temperatures, use lithium batteries for longer battery life. Extensive use of screen backlighting will significantly reduce battery life.
Optional Accessories

The following accessories are available from your GARMIN Dealer or directly from GARMIN. To order from GARMIN, call (913) 397-8200 between 8 a.m. and 5 p.m. CST.

Swivel Mount Bracket .......... Part No. 010-10048-00
Mount will swivel at base (360°) and can be tilted (30°).

Bicycle Mount .................. Part No. 010-10115-00
Allows the GPS 12 MAP to mount on a bicycle handlebar.

Carrying Case ................. Part No. 010-10117-01
Zippered Case is lined and has a belt loop.

GA 27C Amplified Antenna ... Part No. 010-10052-05
Allows operation of the GPS 12 MAP inside a vehicle.

Trunk Lip Antenna Mount ... Part No. 010-10061-00

Flange Antenna Mount ....... Part No. 010-10062-00

AC Adapter (US) ............... Part No. 362-00018-00

Cigarette Lighter Adapter .... Part No. 010-10085-00
Plugs into 12 and 24 VDC to run on external power.

Power Data Cable .............. Part No. 010-10082-00
Bare wire connection. (Not shown)

Data Transfer Cable (Unit to Unit) .............. Part No. 010-10142-00

PC Interface Cable (RS 232 Serial connector only) .......... Part No. 010-10141-00

PC Interface Cable with Cigarette Lighter Adapter (RS 232 Serial connector) ........ Part No. 010-10165-00

MapSource CD ROM’s (Not shown)
US Roads and Recreation ...... Part No. 010-10215-00
World Map ....................... Part No. 010-10215-01
United States Topo .............. Part No. 010-10215-02
Metro Guide U.S.A. ............. Part No. 010-10215-03
U.S. Waterways & Lights ........ Part No. 010-10215-05

For availability and additional accessories contact your GARMIN Dealer or the GARMIN website at www.garmin.com.
Interfacing formats are selected from the Setup Menu, described on page 79. The input/output lines on your GPS 12 MAP are RS-232 compatible allowing easy interface to a wide range of external devices, including PCs, differential beacon receivers, marine autopilots and/or a second GPS receiver.

The NMEA 0183 version 2.3 interface format is supported by the GPS 12 MAP and enables the unit to drive up to three NMEA devices:

- NMEA 0183 version 2.3 Approved sentences:
  - GPGGA, GPGLL, GPGSA, GPGSV, GPRMB, GPRMC, GPRTE, GPWPL, GPBOD

- Proprietary sentences:
  - PGRME (estimated error), PGRMM (map datum), PGRMZ (altitude), PSLIB (beacon receiver control)

DGPS (Differential GPS) corrections are accepted in RTCM SC-104 version 2.0 format through the Data In line. A GARMIN Differential Beacon Receiver (such as the GBR 21) is recommended for use with the GPS 12 MAP. Other beacon receivers with the correct RTCM format may be used, but may not correctly display status or allow tuning control from the GPS unit.

The GPS 12 MAP may be hard-wired to a vehicle’s electrical system (10-32 VDC) using an optional power/data cable. Consult the wiring diagram to the right for proper connections. (The male connector on the back of the GPS 12 MAP is illustrated.) A cigarette lighter adapter is also available to power your GPS 12 MAP without making permanent connections.

Additional cables are available to connect your GPS 12 MAP to a PC-compatible computer’s serial port (PC Interface Cable) or to connect to a second GPS 12 MAP (Data Cross-Load Cable). Contact your GARMIN dealer for any of these accessories.
The GPS 12 MAP uses an on-screen message indicator to alert you to important information. Whenever the message appears, press ENTER to acknowledge the message and return to the previous page you were viewing. Messages are provided for system status, waypoint/route editing, battery condition, etc. For your safety, pay careful attention to all messages.

**Alarm Clock**—The alarm clock time that was set from the Alarms submenu has been reached.

**Approaching**—You are one minute away from reaching a destination waypoint.

**Arrival at**—You have reached your destination waypoint.

**Battery Power Low**—The batteries are low and should be replaced.

**Data Transfer Complete**—The unit has finished uploading or downloading information to the connected device.

**Degraded Accuracy**—The unit’s accuracy has been degraded beyond 500 meters due to poor satellite geometry or data quality. Check other navigational sources to verify the position indicated.

**Leg not Smoothed**—The upcoming route leg is too short for smooth waypoint transitions.

**Memory Battery Power Low**—The battery that sustains user memory is low and should be replaced by an authorized service center as soon as possible. Failure to do so may result in loss of stored data, including all user waypoints and routes. **NOTE:** This message may also appear if the unit has been stored without batteries for a period of 3-4 months. Inserting new batteries, or operating from auxiliary power for 24 hours will recharge the internal memory battery.

**Need Altitude for 2D Nav**—The unit needs altitude input in order to start and/or continue 2D navigation.

**Need to Select Init Method**—You must select an initialization method so the unit can locate satellites and obtain a fix.

**No Differential GPS Position**—Not enough data is available to compute a DGPS position.

**No RTCM Input**—Beacon receiver is improperly connected or baud rates do not match.
Off Course Alarm—You are left or right of course, beyond the limits set on the Alarms submenu.

Oscillator Needs Adjustment—The GPS 12 MAP has detected excessive drift in its internal crystal oscillator which may result in longer acquisition time. The unit should be taken to an authorized GARMIN service center.

Poor GPS Coverage—The unit cannot acquire the necessary number of satellites to compute a position. Try another location with a clearer view of the sky.

Power Down and Re-init—The unit cannot calculate a position due to abnormal satellite conditions. Turn power off and use other means to verify the last position shown. Try the unit again later, possibly in a different location.

RAM Failed—The GPS 12 MAP has detected a failure in its internal memory. If the message persists, the GPS 12 MAP is unusable and should be taken to an authorized GARMIN service center.

Received Invalid Waypoint—A waypoint was received during upload transfer that has an invalid identifier.

Receiver Failed—A failure in receiver hardware has been detected. If this message persists, do not use the unit and take it to an authorized dealer for repair.

ROM Failed—The permanent memory has failed and the unit is not operable. Take your unit to an authorized GARMIN dealer for repairs.

Route Already Exists—You have attempted to name a route with the same name currently in use with an existing route. Enter a different name for the route.

Route Full—You have attempted to add more than 30 waypoints to a route.

Route Memory Full—Route memory is full and no additional routes can be added from another GPS 12 MAP or uploaded from a PC.
Route Waypoint Deleted—The waypoint being deleted was part of a route. The deleted waypoint is removed from waypoint memory and from the route.

RTCM Input Failed—DGPS data being received has been lost. You are no longer receiving the beacon signal.

Searching the Sky—The GPS 12 MAP is searching the sky for almanac data or the unit is in AutoLocate mode.

Steep Turn Ahead—(Aviation) This message appears approximately one minute prior to a turn that requires a bank angle in excess of 25 degrees in order to stay on course.

Stored Data Lost—All waypoints, routes, time, and almanac data have been lost due to battery failure, or the receiver’s memory has been cleared.

Timer Expired—The countdown timer has expired.

Track Log Already Exists—The name selected for the track log is identical to another track log already stored in memory.

Track Memory Full—You have used all track log points in the GPS 12 MAP. (The unit holds approximately 1900 points in the active track log.) Delete unwanted track points to make room for new entries.

Using Simulator for Faster Data Transfer—While using the PC Software Kit or the MapSource program, simulator mode is automatically selected to enable a higher data transfer rate.

Waypoint Memory Full—You have used all 500 waypoints in the GPS 12 MAP. Delete unwanted waypoints to make room for new entries.

Waypoint Already Exists—The name you are entering already exists in the GPS 12 MAP’s memory.
### Time Offset Chart

The table below gives approximate UTC time offset for various longitudinal zones. If you are in daylight savings time, add one hour to the offset.

<table>
<thead>
<tr>
<th>Longitudinal Zone</th>
<th>Offset</th>
<th>Longitudinal Zone</th>
<th>Offset</th>
</tr>
</thead>
<tbody>
<tr>
<td>W180.0° to W172.5°</td>
<td>-12</td>
<td>E007.5° to E022.5°</td>
<td>+1</td>
</tr>
<tr>
<td>W172.5° to W157.5°</td>
<td>-11</td>
<td>E022.5° to E037.5°</td>
<td>+2</td>
</tr>
<tr>
<td>W157.5° to W142.5°</td>
<td>-10</td>
<td>E037.5° to E052.5°</td>
<td>+3</td>
</tr>
<tr>
<td>W142.5° to W127.5°</td>
<td>-9</td>
<td>E052.5° to E067.5°</td>
<td>+4</td>
</tr>
<tr>
<td>W127.5° to W112.5°</td>
<td>-8</td>
<td>E067.5° to E082.5°</td>
<td>+5</td>
</tr>
<tr>
<td>W112.5° to W097.5°</td>
<td>-7</td>
<td>E082.5° to E097.5°</td>
<td>+6</td>
</tr>
<tr>
<td>W097.5° to W082.5°</td>
<td>-6</td>
<td>E097.5° to E112.5°</td>
<td>+7</td>
</tr>
<tr>
<td>W082.5° to W067.5°</td>
<td>-5</td>
<td>E112.5° to E127.5°</td>
<td>+8</td>
</tr>
<tr>
<td>W067.5° to W052.5°</td>
<td>-4</td>
<td>E127.5° to E142.5°</td>
<td>+9</td>
</tr>
<tr>
<td>W052.5° to W037.5°</td>
<td>-3</td>
<td>E142.5° to E157.5°</td>
<td>+10</td>
</tr>
<tr>
<td>W037.5° to W022.5°</td>
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<td>E157.5° to E172.5°</td>
<td>+11</td>
</tr>
<tr>
<td>W022.5° to W007.5°</td>
<td>-1</td>
<td>E172.5° to E180.0°</td>
<td>+12</td>
</tr>
<tr>
<td>W007.5° to E007.5°</td>
<td>0</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
## APPENDIX F
### Map Datums

The following are the map datums available for the GPS12 MAP. Menu Page abbreviations are listed first, followed by the corresponding map datum name and area. The default map datum for the GPS 12 MAP is WGS 84.

<table>
<thead>
<tr>
<th>Map Datum</th>
<th>Area</th>
</tr>
</thead>
<tbody>
<tr>
<td>Adindan</td>
<td>Adindan- Ethiopia, Mali, Senegal, Sudan</td>
</tr>
<tr>
<td>Algooye</td>
<td>Algooye - Somalia</td>
</tr>
<tr>
<td>AIN EL ABD ’70</td>
<td>AIN EL ANBD 1970- Bahrain Island, Saudi Arabia</td>
</tr>
<tr>
<td>Anna I Ast ’65</td>
<td>Anna I Astro ’65- Cocos Isl.</td>
</tr>
<tr>
<td>ARC 1950</td>
<td>ARC 1950- Botswana, Lesotho, Malawi, Swaziland, Zaire, Zambia, Zimbabwe</td>
</tr>
<tr>
<td>ARC 1960</td>
<td>ARC 1960- Kenya, Tanzania</td>
</tr>
<tr>
<td>Ascnsn Isld ’58</td>
<td>Ascension Island ’58- Ascension Island</td>
</tr>
<tr>
<td>Astro B4 Sorol</td>
<td>Astro B4 Sorol Atoll- Tin Island</td>
</tr>
<tr>
<td>Astro Bcn “E”</td>
<td>Astro Beacon “E”- Iwo Jima</td>
</tr>
<tr>
<td>Astro Dos 71/4</td>
<td>Astro Dos 71/4- St. Helena</td>
</tr>
<tr>
<td>Astr Stn ’52</td>
<td>Astronomic Stn ’52- Marcus Island</td>
</tr>
<tr>
<td>Astrln Geod ’66</td>
<td>Australian Geod ’66- Australia, Tasmania Island</td>
</tr>
<tr>
<td>Astrln Geod ’84</td>
<td>Australian Geod ’84- Australia, Tasmania Island</td>
</tr>
<tr>
<td>Bellevue (IGN)</td>
<td>Elate and Erromango Islands</td>
</tr>
<tr>
<td>Bermuda 1957</td>
<td>Bermuda 1957- Bermuda Islands</td>
</tr>
<tr>
<td>Bogata Observ</td>
<td>Bogata Obsrvarry- Colombia</td>
</tr>
<tr>
<td>Campo Incluspe</td>
<td>Campo Inchauspe- Argentina</td>
</tr>
<tr>
<td>Canton Ast ’66</td>
<td>Canton Astro 1966- Phoenix Islands</td>
</tr>
<tr>
<td>Cape</td>
<td>Cape- South Africa</td>
</tr>
<tr>
<td>Cape Canavl</td>
<td>Cape Canaveral- Florida, Bahama Islands</td>
</tr>
<tr>
<td>Carthage</td>
<td>Carthage- Tunisia</td>
</tr>
<tr>
<td>CH-1903</td>
<td>CH 1903- Switzerland</td>
</tr>
<tr>
<td>Chatham 1971</td>
<td>Chatham 1971- Chatham Island (New Zealand)</td>
</tr>
<tr>
<td>Chua Astro</td>
<td>Chua Astro- Paraguay</td>
</tr>
<tr>
<td>Corrego Alegre</td>
<td>Corrego Alegre- Brazil</td>
</tr>
<tr>
<td>Djakarta</td>
<td>Djakarta (Batavia)- Sumatra Island (Indonesia)</td>
</tr>
<tr>
<td>Dos 1968</td>
<td>Dos 1968- Gizo Island (New Georgia Islands)</td>
</tr>
<tr>
<td>Easter Isld 67</td>
<td>Easter Island 1967</td>
</tr>
<tr>
<td>European 1950</td>
<td>European 1950- Austria, Belgium, Denmark, Finland, France, Germany, Gibraltar, Greece, Italy, Luxembourg, Netherlands, Norway, Portugal, Spain, Sweden, Switzerland</td>
</tr>
<tr>
<td>European 1979</td>
<td>European 1979- Austria, Finland, Netherlands, Norway, Spain, Sweden, Switzerland</td>
</tr>
<tr>
<td>Finland Hayfnd</td>
<td>Finland Hayford- Finland</td>
</tr>
<tr>
<td>Gandajika Base</td>
<td>Gandajika Base- Republic of Maldives</td>
</tr>
<tr>
<td>Geod Darm ’49</td>
<td>Geodetic Datum ‘49- New Zealand</td>
</tr>
<tr>
<td>Guam 1963</td>
<td>Guam 1963- Guam Island</td>
</tr>
<tr>
<td>Map Datums</td>
<td>Description</td>
</tr>
<tr>
<td>---------------------</td>
<td>--------------------------------------------------</td>
</tr>
<tr>
<td>Gux 1 Astro Guadalcanal Island</td>
<td>Guadalcanal Island</td>
</tr>
<tr>
<td>Hjorsey 1955</td>
<td>Iceland</td>
</tr>
<tr>
<td>Hong Kong '63</td>
<td>Hong Kong</td>
</tr>
<tr>
<td>Hu-Tzu-Shan</td>
<td>Taiwan</td>
</tr>
<tr>
<td>Indian English</td>
<td>Bangladesh, India, Nepal</td>
</tr>
<tr>
<td>Indian Thailand</td>
<td>Vietnam</td>
</tr>
<tr>
<td>Indonesia '74</td>
<td>Indonesia</td>
</tr>
<tr>
<td>Ireland 1965</td>
<td>Ireland</td>
</tr>
<tr>
<td>ISTS 073 Astro</td>
<td>ISTS 073 ASTRO '69-Diego Garcia</td>
</tr>
<tr>
<td>Johnston Island</td>
<td>Johnston Island</td>
</tr>
<tr>
<td>Kerguelen Island</td>
<td>Kerguelen Island</td>
</tr>
<tr>
<td>Kertau 1948</td>
<td>Kertau 1948-West Malaysia, Singapore</td>
</tr>
<tr>
<td>L. C. 5 Astro</td>
<td>Cayman Brac Island</td>
</tr>
<tr>
<td>Liberia 1964</td>
<td>Liberia 1964-Libera</td>
</tr>
<tr>
<td>Luzon Mindanao</td>
<td>Luzon-Mindanao Island</td>
</tr>
<tr>
<td>Luzon Philippine</td>
<td>Luzon-Philippines (excluding Mindanao Island)</td>
</tr>
<tr>
<td>Mahe 1971</td>
<td>Mahe 1971-Mahe Island</td>
</tr>
<tr>
<td>Marco Astro</td>
<td>Marco Astro-Salvage Island</td>
</tr>
<tr>
<td>Massawa</td>
<td>Massawa-Eritrea (Ethiopia)</td>
</tr>
<tr>
<td>Merchich</td>
<td>Merchich-Morocco</td>
</tr>
<tr>
<td>Midway Ast '61</td>
<td>Midway Astro '61-Midway</td>
</tr>
<tr>
<td>Minna</td>
<td>Minna-Nigeria</td>
</tr>
<tr>
<td>NAD27 Alaska</td>
<td>North American 1927-Alaska</td>
</tr>
<tr>
<td>NAD27 Bahamas</td>
<td>North American 1927-Bahamas (excluding San Salvador Island)</td>
</tr>
<tr>
<td>NAD27 Canada</td>
<td>North American 1927-Canada and Newfound-Canada</td>
</tr>
<tr>
<td>NAD27 Canal Zone</td>
<td>North American 1927-Canal Zone</td>
</tr>
<tr>
<td>NAD27 Caribbean</td>
<td>North American 1927-Caribbean (Barbados, Caicos Islands, Cuba, Dom. Rep., Grand Cayman, Jamaica, Leeward and Turks Islands)</td>
</tr>
<tr>
<td>NAD27 Central</td>
<td>North American 1927-Central America (Belize, Costa Rica, El Salvador, Guatemala, Honduras, Nicaragua)</td>
</tr>
<tr>
<td>NAD27 CONUS</td>
<td>North American 1927-Mean Value</td>
</tr>
<tr>
<td>NAD27 Cuba</td>
<td>North American 1927-Cuba</td>
</tr>
<tr>
<td>NAD27 Greenland</td>
<td>North American 1927-Greenland (Hayes Peninsula)</td>
</tr>
<tr>
<td>NAD27 Mexico</td>
<td>North American 1927-Mexico</td>
</tr>
<tr>
<td>NAD27 San Salvador</td>
<td>North American 1927-San Salvador Island</td>
</tr>
<tr>
<td>NAD83</td>
<td>North American 1983-Alaska, Canada, Central America, CONUS, Mexico</td>
</tr>
<tr>
<td>Nahrwn Masirah</td>
<td>Nahrwn-Masirah Island (Oman)</td>
</tr>
<tr>
<td>Nahrwn Saudi A</td>
<td>Nahrwn-Saudi Arabia</td>
</tr>
<tr>
<td>Nahrwn United A</td>
<td>Nahrwn-United Arab Emirates</td>
</tr>
<tr>
<td>Naparima BWI</td>
<td>Naparima BWI-Trinidad and Tobago</td>
</tr>
</tbody>
</table>
### Map Datums

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Obsrvtorio '66</td>
<td>Observatorio 1966- Corvo and Flores Islands (Azores)</td>
</tr>
<tr>
<td>Old Egyptian</td>
<td>Old Egyptian- Egypt</td>
</tr>
<tr>
<td>Old Hawaiian</td>
<td>Old Hawaiian- Mean Value</td>
</tr>
<tr>
<td>Oman</td>
<td>Oman- Oman</td>
</tr>
<tr>
<td>Ord Srvy GB</td>
<td>Old Survey Grt Brtn- England, Isle of Man, Scotland, Shetland Isl., Wales</td>
</tr>
<tr>
<td>Pico De Las Nv</td>
<td>Canary Islands</td>
</tr>
<tr>
<td>Pitcairn Ast '67</td>
<td>Pitcairn Astro '67- Pitcairn Isl.</td>
</tr>
<tr>
<td>Prov S Am '56</td>
<td>Prov So Amric '56- Bolivia, Chile, Colombia, Ecuador, Guyana, Peru, Venezuela</td>
</tr>
<tr>
<td>Prov S Chln '63</td>
<td>Prov So Chilean '63- S. Chile</td>
</tr>
<tr>
<td>Puerto Rico</td>
<td>Puerto Rico &amp; Virgin Islands</td>
</tr>
<tr>
<td>Qatar National</td>
<td>Qatar National- Qatar</td>
</tr>
<tr>
<td>Qornoq</td>
<td>Qornoq- South Greenland</td>
</tr>
<tr>
<td>Reunion</td>
<td>Reunion- Mascarene Island</td>
</tr>
<tr>
<td>Rome 1940</td>
<td>Rome 1940- Sardinia Island</td>
</tr>
<tr>
<td>RT 90</td>
<td>Sweden</td>
</tr>
<tr>
<td>Santo (Dos)</td>
<td>Santo (Dos)- Espirito Santo Island</td>
</tr>
<tr>
<td>Sao Braz</td>
<td>Sao Braz- Sao Miguel, Santa Maria Islands (Azores)</td>
</tr>
<tr>
<td>Sapper Hill '43</td>
<td>Sapper Hill 1943- East Falkland Island</td>
</tr>
<tr>
<td>Schwarzeck</td>
<td>Schwarzeck- Namibia</td>
</tr>
<tr>
<td>Sth Amrcn '69</td>
<td>South American '69- Argentina, Bolivia, Brazil, Chile, Colombia, Ecuador,</td>
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<tr>
<td></td>
<td>Guyana, Paraguay, Peru, Venezuela, Trinidad and Tobago</td>
</tr>
<tr>
<td>South Asia</td>
<td>South Asia- Singapore</td>
</tr>
<tr>
<td>SE Base</td>
<td>Southeast Base- Porto Santo and Madiera Islands</td>
</tr>
<tr>
<td>SW Base</td>
<td>Southwest Base- Faial, Graciosa, Pico, Sao Jorge and Terceira Islands</td>
</tr>
<tr>
<td></td>
<td>(Azores)</td>
</tr>
<tr>
<td>Timbalai 1948</td>
<td>Timbalai 1948- Brunei and E. Malaysia (Sarawak and Sabah)</td>
</tr>
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**Landmark Log:**
Use this space to record Landmarks that you want to retain for use in the future, but are deleting from the waypoint list contained in the GPS 12 MAP to make space for new, more active waypoints.

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**Record your unit Serial No.:**
Record your unit Serial No. to speed recovery if lost or stolen and for warranty service.

**Notes:**
Use this space to record notes about each landmark, such as date, description, etc.
Product Registration

Help us to better support you by completing our on-line registration today!
Have the serial number of your GPS 12 MAP handy and connect to our website (www.garmin.com). Look for the Product Registration link on the Home Page.

Why should you register your GPS 12 MAP unit?
- Notification of Product Updates
- Notification of New Products
- Lost or Stolen unit tracking

NOTE: If you have previously registered your GARMIN product purchase using a mail-in registration card, we invite you to re-register using our NEW on-line system. Many services provided by our new product registration system are now being automated and re-registering your purchase ensures you the best possible support from GARMIN.

Serial Number
Use this area to record the serial number (8-digit number located on the back of the unit) in case it is lost, stolen, or needs service. Be sure to keep your original sales receipt in a safe place or attach a photocopy inside the manual.

Serial Number: * *